Extended QRGCD Algorithm

Kosaku Nagasaka and Takaaki Masui

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09:30-10:00, September 10th

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Extended QRGCD Algorithm

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What is "approximate GCD"?

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GCD (Greatest Common Divisor) \leftarrow Exact GCD

$$f(x) = x^2 + 2x + 1, \ g(x) = x^2 - 1 \ \Rightarrow \ \gcd(f,g) = x + 1$$

The polynomial of maximum degree, which divides f(x) and g(x).

Approximate GCD (Greatest Common Divisor)

 $f(x) = 0.999x^{2} + 1.999x + 1.001, g(x) = 1.001x^{2} - 0.999$ $\Rightarrow \gcd(f,g) = 1 \quad (coprime)$ $\Rightarrow \gcd(f,g) = 1.00063x + 0.999375$ $= \gcd(f + (-0.0003343x^{2} + 0.0003347x - 0.0003351), g + (0.0001666x^{2} - 0.0001669x + 0.0001671))$

GCD with some consideration of a priori error (perturbation)

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 $\mathsf{GCD} \; (\mathsf{Greatest} \; \mathsf{Common} \; \mathsf{Divisor}) \Leftarrow \mathsf{Exact} \; \mathsf{GCD}$

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The polynol Adding Some Noise ree, which divides f(x) and g(x).

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GCD with some consideration of a priori error (perturbation) hence it's a GCD in the neighborhood of the given polynomials

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GCD with some consideration of a priori error (perturbation) hence it's a GCD in the neighborhood of the given polynomials.

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Extended QRGCD Algorithm

Problem Formulation of approximate GCD

Given: $f(x), g(x) \in \mathbb{R}[x]$, tolerance $\varepsilon \in \mathbb{R}_{\geq 0}$ ($\mathbb{R}[x]$ could be $\mathbb{C}[x]$) Find: $d(x) \in \mathbb{R}[x]$ ($\Delta_f(x), \Delta_g(x), f_1(x), g_1(x) \in \mathbb{R}[x]$)

 $f(x) + \Delta_f(x) = f_1(x)d(x), \ g(x) + \Delta_g(x) = g_1(x)d(x)$

 $\deg(\Delta_f) \leq \deg(f), \deg(\Delta_g) \leq \deg(g), \ \|\Delta_f\|_2 < \varepsilon \|f\|_2, \|\Delta_g\|_2 < \varepsilon \|g\|_2$

d(x): approximate GCD, $f_1(x)$ and $g_1(x)$: approximate cofactors, $\Delta_f(x)$ and $\Delta_g(x)$: perturbations

Example: $f(x) = 0.999x^2 + 1.999x + 1.001$, $g(x) = 1.001x^2 - 0.999$

 $d(x) = 1.00063x + 0.999375, \ \varepsilon = 0.0005796959,$ $f_1(x) = 0.998042x + 1.00129, \ g_1(x) = 1.00054x - 0.999458,$ $\Delta_f(x) = -0.000334269x^2 + 0.000334687x - 0.000335106,$ $\Delta_g(x) = 0.000166643x^2 - 0.000166851x + 0.00016706$

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Given: $f(x), g(x) \in \mathbb{R}[x]$, tolerance $\varepsilon \in \mathbb{R}_{\geq 0}$ ($\mathbb{R}[x]$ could be $\mathbb{C}[x]$) Find: $d(x) \in \mathbb{R}[x]$ ($\Delta_f(x), \Delta_g(x), f_1(x), g_1(x) \in \mathbb{R}[x]$)

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Example: $f(x) = 0.999x^2 + 1.999x + 1.001$, $g(x) = 1.001x^2 - 0.999$

$$\begin{split} &d(x) = 1.00063x + 0.999375, \ \varepsilon = 0.0005796959, \\ &f_1(x) = 0.998042x + 1.00129, \ g_1(x) = 1.00054x - 0.999458, \\ &\Delta_f(x) = -0.000334269x^2 + 0.000334687x - 0.000335106, \\ &\Delta_g(x) = 0.000166643x^2 - 0.000166851x + 0.00016706 \end{split}$$

QRGCD (by R.M.Corless, S.M.Watt and L.Zhi, 2004) (widely used)

QR factoring of Sylvester matrix (PRS appear on rows of *R*).
Do this twice (QR factoring detects roots inside the unit circle).

UVGCD (by Z.Zeng, 2004 and 2011)

(stable for multiple roots)

 QR factoring of subresultant matrices (for the smallest singular value and the corresponding vector)
 Tentative approximate GCD by the least squares.
 Refine approximate GCD by the Gauss-Newton method.

Fastgcd (by D.A.Bini and P.Boito, 2007 and 2010) (fast and stable)

Based on the LU factoring of Sylvester matrix (Toeplitz block).
 Transform it into Cauchy-like matrix and use a modified GKO (Gohberg-Kailath-Olshevsky) method for LU factoring.
 Refine approximate GCD by some refinement method.

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Brief framework of QRGCD.

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Extended QRGCD Algorithm

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Brief framework of the QRGCD algorithm

Sylvester matrix (in this talk)

$$f(x) = f_m x^m + f_{m-1} x^{m-1} + \dots + f_1 x + f_0,$$

$$g(x) = g_n x^n + g_{n-1} x^{n-1} + \dots + g_1 x + g_0,$$

$$\operatorname{Syl}(f,g) = \begin{pmatrix} f_m & f_{m-1} & \cdots & f_1 & f_0 & & \\ & f_m & f_{m-1} & \cdots & f_1 & f_0 & & \\ & & \ddots & \ddots & \ddots & \ddots & \ddots & \\ & & & f_m & f_{m-1} & \cdots & f_1 & f_0 \\ g_n & g_{n-1} & \cdots & g_1 & g_0 & & \\ & & & \ddots & \ddots & \ddots & \ddots & \\ & & & & g_n & g_{n-1} & \cdots & g_1 & g_0 \end{pmatrix}$$

$$\in \mathbb{C}^{(m+n) \times (m+n)}$$



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 $\ell = m + n$



(the reversal of h(x) is defined by $\operatorname{rev}(h) = h(x) \mapsto x^{\operatorname{deg}(h)}h(1/x)$) $\widetilde{\ell} = \operatorname{deg}(f_1) + \operatorname{deg}(g_1)$





$$\frac{\|R^{(k-1)}\|_2}{\|R^{(k)}\|_2} < 10\varepsilon \Longrightarrow d_2(x) := \operatorname{rev}(r_{\tilde{\ell}-k,\tilde{\ell}-k}x^k + \dots + r_{\tilde{\ell}-k,\tilde{\ell}-1}x + r_{\tilde{\ell}-k,\tilde{\ell}})$$

Done twice (Normal and Reversal sides) $\tilde{\ell} = \deg(f_1) + \deg(g_1)$

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Extended QRGCD Algorithm

The QRGCD algorithm (briefly described)

1 Compute the QR decomposition of Syl(f, g): Syl(f, g) = QR

2 For integer k satisfying $||R^{(k)}||_2 > \varepsilon$ and $||R^{(k-1)}||_2 < \varepsilon$, do

Case1: approximately coprime

 $||R^{(0)}||_{2} > \varepsilon$

Case2: absolute and relative gap found

 $\frac{\|R^{(k-1)}\|_2}{\|R^{(k)}\|_2} < 10\varepsilon \Longrightarrow d(x) := \text{the last } k\text{-th row of } R$

Case3: relative gap found

$$\exists k_1, \ \frac{\|R^{(k_1-1)}\|_2}{\|R^{(k_1)}\|_2} < 10\varepsilon \Longrightarrow d(x) := \mathsf{last} \ k_1\mathsf{-th} \ \mathsf{row}$$

Case4: no gap found but not coprime

Otherwise (we will call the Split algorithm)

3 Do the above for the reversals of approximate cofactors. (the reversal of h(x) is defined by $h(x) \mapsto x^{\deg(h)}h(1/x)$)

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How to find candidates of approximate GCD

- **QRGCD** seeks a row of R, which is absolutely close to d(x).
- This allows the QRGCD algorithm to detect a polynomial whose structure is <u>far</u> from the nearest approximate GCD.

\implies It should be a relative closeness instead of absolute one.

How to determine an approximate GCD among candidates

- QRGCD tries to detect a factor of maximum degree at once.
- This has a non-preferred effect which was not shown in QRGCD.
 - It may detect a <u>fake</u> common root inside the unit circle.
 - It may output a polynomial with $\|\Delta_f\| > \varepsilon \|f\|$, $\|\Delta_g\| > \varepsilon \|g\|$.

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 - It may detect a <u>fake</u> common root inside the unit circle.
 - It may output a polynomial with $\|\Delta_f\| > \varepsilon \|f\|$, $\|\Delta_g\| > \varepsilon \|g\|$.

 \implies It should be a factor with small perturbations regardless degrees.

How improved in ExQRGCD?

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Extended QRGCD Algorithm

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Important fact (1) used in our ExQRGCD

Relative closeness of the rows of R to the approximate GCD

Let r(x) be a polynomial with coefficients \vec{r} which is a row of R, and $d_r(x)$ be a factor of d(x), whose roots are $\{\omega_1, \ldots, \omega_k\}$. Then, an upper bound of relative distance of r(x) from $d_r(x)$ is given by

$$\frac{\parallel r(x) - d_r(x) \parallel_2}{\parallel r(x) \parallel_2} \leq \sqrt{k+1} \kappa_2(\Omega_*(d_r)) \frac{\parallel \operatorname{Syl}(\Delta_f, \Delta_g) \parallel_2}{\parallel r(x) \parallel_2}$$

where $\Omega_*(d_r)$ is the matrix in $\mathbb{C}^{k \times (m+n)}$, whose (i, j)-element is ω_i^{m+n-j} , and $\kappa_2(\Omega_*(d_r))$ denotes the condition number of $\Omega_*(d_r)$.

$$\implies \mathsf{ExQRGCD} \text{ seeks a row } \vec{r_k} \text{ such that } \frac{\|R^{(k-1)}\|_2}{\|r_k\|_2} \text{ is small.}$$

(instead of $\frac{\|R^{(k-1)}\|_2}{\|R^{(k)}\|_2}$ in QRGCD)

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Important fact (2) used in our ExQRGCD

QR factoring may not detect common roots outside the unit circle

There exists a pair of polynomials f(x) and g(x) such that the QR decomposition of Syl(f,g) cannot detect any outside-root factor of the approximate GCD. Moreover, we need to detect such factors from rev(f) and rev(g) or their cofactors several times and combine them.

Note that rev(h) is defined by $h(x) \mapsto x^{\deg(h)}h(1/x)$.

Please note that the same claim is also given in the original QRGCD. Our result is that we proved it more carefully by the different way (based on a property of Sylvester's single sum).

 $\implies \mathsf{ExQRGCD} \text{ seeks a row } \vec{r_k} \text{ such that the resulting perturbations} \\ \Delta_f \text{ and } \Delta_g \text{ are smallest among the candidates.}$

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$$d(x) = 1, \ f_1(x) = f(x), \ g_1(x) = g(x)$$

Syl $(f_1, g_1) =$

$$\begin{pmatrix} r_{1,1} & r_{1,2} & \cdots & \cdots & r_{1,\ell} \\ & r_{2,2} & r_{2,3} & \cdots & \cdots & r_{2,\ell} \\ & \ddots & \ddots & \ddots & \ddots & \vdots \\ & & r_{\ell-k,\ell-k} & r_{\ell-k,\ell-k+1} & \cdots & r_{\ell-k,\ell} \\ & & & r_{\ell-(k-1),\ell-(k-1)} & \cdots & r_{\ell-(k-1),\ell} \\ & & & \ddots & \vdots \\ & & & & r_{\ell,\ell} \end{pmatrix}$$

 $d_1(x) := r_k(x)$ s.t. the corresponding $\vec{r_k}$ meets the condition that $rac{\|R^{(k-1)}\|_2}{\|r_k\|_2} \ll 1$ and (Δ_f, Δ_g) w.r.t. $d_1(x)$ satisfies the tolerance.

$$\ell = \mathsf{deg}(f_1) + \mathsf{deg}(g_1)$$

$$d(x) = 1, \ f_{1}(x) = f(x), \ g_{1}(x) = g(x)$$

Syl(f_{1}, g_{1}) =

$$\begin{pmatrix} r_{1,1} & r_{1,2} & \cdots & \cdots & r_{1,\ell} \\ r_{2,2} & r_{2,3} & \cdots & \cdots & r_{2,\ell} \\ & \ddots & \ddots & \ddots & \ddots & \vdots \\ \hline \vec{r_{k}} & r_{\ell-k,\ell-k} & r_{\ell-k,\ell-k+1} & \cdots & r_{\ell-k,\ell} \\ & & & & & & \\ \hline r_{\ell-(k-1),\ell-(k-1)} & \cdots & r_{\ell-(k-1),\ell} \\ & & & & & & \\ \hline r_{\ell-(k-1)} & & & & & \\ \hline r_{\ell,\ell} \end{pmatrix}$$

 $d_1(x) := r_k(x)$ s.t. the corresponding $\vec{r_k}$ meets the condition that $\frac{\|R^{(k-1)}\|_2}{\|r_k\|_2} \ll 1$ and (Δ_f, Δ_g) w.r.t. $d_1(x)$ satisfies the tolerance. $\ell = \deg(f_1) + \deg(g_1)$ Q

How our ExQRGCD algorithm works

$$d(x) = d_1(x), \ f_2(x) = f(x) \div d(x), \ g_2(x) = g(x) \div d(x)$$

Syl(rev(f_2), rev(g_2)) =
 $(r_{1,1}, r_{1,2}, \cdots, \cdots, r_{1,\ell})$

 $d_2(x) := r_k(x)$ s.t. the corresponding $\vec{r_k}$ meets the condition that $\frac{\|R^{(k-1)}\|_2}{\|r_k\|_2} \ll 1$ and (Δ_f, Δ_g) w.r.t. $d_1(x)d_2(x)$ satisfies the tolerance.

$$\ell = \deg(f_2) + \deg(g_2)$$

Q

How our ExQRGCD algorithm works

$$d(x) = d_1(x), \ f_2(x) = f(x) \div d(x), \ g_2(x) = g(x) \div d(x)$$

Syl(rev(f_2), rev(g_2)) =
$$\begin{pmatrix} r_{1,1} & r_{1,2} & \cdots & \cdots & \cdots \\ & r_{2,2} & r_{2,3} & \cdots & \cdots & \cdots \end{pmatrix}$$

$$\begin{pmatrix} r_{1,1} & r_{1,2} & \cdots & \cdots & r_{1,\ell} \\ r_{2,2} & r_{2,3} & \cdots & \cdots & r_{2,\ell} \\ \vdots & \vdots & \ddots & \vdots \\ \vec{r_k} & r_{\ell-k,\ell-k} & r_{\ell-k,\ell-k+1} & \cdots & r_{\ell-k,\ell} \\ & & & & \\ r_{\ell-(k-1),\ell-(k-1)} & \cdots & r_{\ell-(k-1),\ell} \\ & & & & \\ \hline & & & & \\ R^{(k-1)} & & & r_{\ell,\ell} \end{pmatrix}$$

 $d_2(x) := r_k(x)$ s.t. the corresponding $\vec{r_k}$ meets the condition that $\frac{\|R^{(k-1)}\|_2}{\|r_k\|_2} \ll 1$ and (Δ_f, Δ_g) w.r.t. $d_1(x)d_2(x)$ satisfies the tolerance. $\ell = \deg(f_2) + \deg(g_2)$

$$d(x) = d_{1}(x)d_{2}(x), \ f_{3}(x) = f(x) \div d(x), \ g_{3}(x) = g(x) \div d(x)$$

Syl(f₃, g₃) =

$$\begin{pmatrix} r_{1,1} & r_{1,2} & \cdots & \cdots & r_{1,\ell} \\ & r_{2,2} & r_{2,3} & \cdots & \cdots & r_{2,\ell} \\ & \ddots & \ddots & \ddots & \ddots & \vdots \\ & & r_{\ell-k,\ell-k} & r_{\ell-k,\ell-k+1} & \cdots & r_{\ell-k,\ell} \\ & & & r_{\ell-(k-1),\ell-(k-1)} & \cdots & r_{\ell-(k-1),\ell} \\ & & & \ddots & \vdots \\ & & & & r_{\ell,\ell} \end{pmatrix}$$

 $d_3(x) := r_k(x)$ s.t. the corresponding $\vec{r_k}$ meets the condition that $rac{\|R^{(k-1)}\|_2}{\|r_k\|_2} \ll 1$ and (Δ_f, Δ_g) w.r.t. $d_1 d_2 d_3$ satisfies the tolerance.

$$\ell = \deg(f_3) + \deg(g_3)$$

$$d(x) = d_{1}(x)d_{2}(x), \ f_{3}(x) = f(x) \div d(x), \ g_{3}(x) = g(x) \div d(x)$$

Syl(f₃, g₃) =

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 $d_3(x) := r_k(x)$ s.t. the corresponding $\vec{r_k}$ meets the condition that $\frac{\|R^{(k-1)}\|_2}{\|r_k\|_2} \ll 1$ and (Δ_f, Δ_g) w.r.t. $d_1d_2d_3$ satisfies the tolerance. $\ell = \deg(f_3) + \deg(g_3)$

 $d(x) = d_1(x)d_2(x)d_3(x), f_4(x) = f(x) \div d(x), g_4(x) = g(x) \div d(x)$ $\operatorname{Syl}(\operatorname{rev}(f_4), \operatorname{rev}(g_4)) =$ $r_{1,1}$ $r_{1,2}$ $r_{2,2}$ $r_{2,3}$... \vdots $r_{1,\ell}$ $r_{2,\ell}$ · · . $\begin{array}{cccc} r_{\ell-k,\ell-k} & r_{\ell-k,\ell-k+1} & \cdots & r_{\ell-k,\ell} \\ & r_{\ell-(k-1),\ell-(k-1)} & \cdots & r_{\ell-(k-1),\ell} \end{array}$ • ree

There is no vector $\vec{r_k}$ satisfying the condition. \implies Approximately coprime w.r.t. the ourside roots.

$$\ell = \deg(f_4) + \deg(g_4)$$

 $d(x) = d_1(x)d_2(x)d_3(x), f_4(x) = f(x) \div d(x), g_4(x) = g(x) \div d(x)$ $\operatorname{Syl}(\operatorname{rev}(f_4), \operatorname{rev}(g_4)) =$ $r_{1,2}$... $r_{2,2}$ $r_{2,3}$ $r_{1,\ell}$ $r_{1,1}$ $r_{2,\ell}$ ۰. ۰. ۰. ۰. $\vec{r_k}$ Q $r_{\ell-k,\ell}$ $r_{\ell-k,\ell-k}$ $r_{\ell-k,\ell-k+1}$ $r_{\ell-(k-1),\ell-(k-1)}$ $r_{\ell-(k-1),\ell}$ $R^{(k-1)}$ r_{e e}

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Syl(f_{4}, g_{4}) =

$$\begin{pmatrix} r_{1,1} & r_{1,2} & \cdots & \cdots & r_{1,\ell} \\ & r_{2,2} & r_{2,3} & \cdots & \cdots & r_{2,\ell} \\ & \ddots & \ddots & \ddots & \ddots & \vdots \\ & & r_{\ell-k,\ell-k} & r_{\ell-k,\ell-k+1} & \cdots & r_{\ell-k,\ell} \\ & & & r_{\ell-(k-1),\ell-(k-1)} & \cdots & r_{\ell-(k-1),\ell} \\ & & & \ddots & \vdots \\ & & & & r_{\ell,\ell} \end{pmatrix}$$

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Syl(f_{4}, g_{4}) =
$$\begin{pmatrix} r_{1,1} & r_{1,2} & \cdots & \cdots & r_{1,\ell} \\ r_{2,2} & r_{2,3} & \cdots & \cdots & r_{2,\ell} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ \hline r_{k} & r_{\ell-k,\ell-k} & r_{\ell-k,\ell-k+1} & \cdots & r_{\ell-k,\ell} \\ \hline r_{\ell-(k-1),\ell-(k-1)} & \cdots & r_{\ell-(k-1),\ell} \\ \hline r_{\ell-(k-1),\ell-(k-1)} & \cdots & r_{\ell-\ell} \end{pmatrix}$$

There is no vector $\vec{r_k}$ satisfying the condition.

 \implies Approximately coprime w.r.t. the inside roots.

$$\ell = \deg(f_4) + \deg(g_4)$$

$$\frac{d(x) = d_1(x)d_2(x)d_3(x), \ f_1(x) = f(x) \div d(x), \ g_1(x) = g(x) \div d(x)}{\operatorname{Syl}(f_4, g_4) =} \\
Q \begin{pmatrix}
r_{1,1} & r_{1,2} & \cdots & \cdots & r_{1,\ell} \\
r_{2,2} & r_{2,3} & \cdots & \cdots & r_{2,\ell} \\
\vdots & \vdots & \vdots \\
\hline r_k & r_{\ell-k,\ell-k} & r_{\ell-k,\ell-k+1} & \cdots & r_{\ell-k,\ell} \\
\hline r_{\ell-(k-1),\ell-(k-1)} & \cdots & r_{\ell-(k-1),\ell} \\
\vdots \\
\hline R^{(k-1)} & r_{\ell,\ell}
\end{pmatrix}$$

There is no vector $\vec{r_k}$ satisfying the condition.

 \implies Approximately coprime w.r.t. the inside roots.

Done several times (Normal, Reversal, Normal, ...)

Our ExQRGCD algorithm (briefly described)

1 Compute the QR decomposition of Syl(f,g): Syl(f,g) = QR**2** Do until $||R^{(k)}||_2 > \varepsilon \sqrt{m+n}$ Case1: approximately coprime $\|R^{(0)}\|_2 > \varepsilon \sqrt{m+n}$ Case2: a factor of approximate GCD found d(x) := r(x) having the smallest $\varepsilon_r = \frac{\|R^{(k-1)}\|_2}{\|r\|_2}$. Case3: no factor found The 3 smallest ε_r s found no factor \Rightarrow **Split** Or goto Step 3 (if #loop > the threshold) (The threshold is 3 in our implementation) 3 Do the above for the reversals of approximate cofactors. (Until approximately coprime is detected twice successively)

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Short Summary: ExQRGCD against QRGCD

Advantage of ExQRGCD

- It seeks approximate GCD within the given tolerance.
- It seeks a factor such that the smallest perturbation

among the candidates.

- \Rightarrow The resulting degree may be larger than QRGCD in general.
- It uses the relative distance bound.
 - \Rightarrow It may not detect a factor having fake common roots.
 - (even when the PRS has some outside roots instead of inside)

Weak point of ExQRGCD

Slower than QRGCD.

since ExQRGCD computes QR factoring several times)

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Extended QRGCD Algorithm

09:30-10:00, September 10th 16 / 23

Short Summary: ExQRGCD against QRGCD

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(since ExQRGCD computes QR factoring several times)

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Numerical Experiments

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Random Polynomials (100 pairs of (f, g) for each i = 1, ..., 10) $f(x) = f_1(x)d(x), g(x) = g_1(x)d(x), d(x) = \sum_{j=0}^{5i} d_j x^j,$ $f_1(x) = \sum_{j=0}^{5i} f_{1,j} x^j, g_1(x) = \sum_{j=0}^{5i} g_{1,j} x^j$ where $f_{1,j}, g_{1,j}, d_j \in [-99, 99] \subset \mathbb{Z}$ is randomly chosen, f(x), g(x)are normalized $(||f||_2 = ||g||_2 = 1)$ and rounded with *Digits* := 10. We computed with tolerance 10^{-5} . Moreover, we used Maple 16 with Digits := 16 on Linux (i7 3.30GHz and 64GB mem.).

Sum of detected degrees The resulting perturbation

■ ExQRGCD is 1.59 times slower than QRGCD.

QRGCD failed 11 times and didn't meet the tolerance 6 times.

Random Polynomials (100 pairs of
$$(f, g)$$
 for each $i = 1, ..., 10$)
 $f(x) = f_1(x)d(x), g(x) = g_1(x)d(x), d(x) = \sum_{j=0}^{5i} d_j x^j,$
 $f_1(x) = \sum_{j=0}^{5i} f_{1,j} x^j, g_1(x) = \sum_{j=0}^{5i} g_{1,j} x^j$



ExQRGCD is 1.59 times slower than QRGCD.
 QRGCD failed 11 times and didn't meet the tolerance 6 times.

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Random Polynomials with Perturbations (100 pairs of (f, g) for *i*) $f(x) = f_1(x)d(x)/||f_1d||_2 + 10^{-8}\Delta_f(x)/||\Delta_f||_2, \ \Delta_f(x) = \sum_{j=0}^{10i} \Delta_{fj}x^j,$ $g(x) = g_1(x)d(x)/||g_1d||_2 + 10^{-8}\Delta_g(x)/||\Delta_g||_2, \ \Delta_g(x) = \sum_{j=0}^{10i} \Delta_{gj}x^j$ where $\Delta_{fj}, \ \Delta_{gj} \in [-99, 99] \subset \mathbb{Z}$ is randomly chosen, $f_1(x), \ g_1(x), \ d(x)$ are the polynomials of the previous Example and rounded with Digits := 10. We computed with tolerance 10^{-5} .

Sum of detected degrees The resulting perturbation

• ExQRGCD is 1.99 times slower than QRGCD.

QRGCD failed 315 times and didn't meet the tolerance 6 times.

Random Polynomials with Perturbations (100 pairs of (f, g) for *i*) $f(x) = f_1(x)d(x)/||f_1d||_2 + 10^{-8}\Delta_f(x)/||\Delta_f||_2, \ \Delta_f(x) = \sum_{j=0}^{10i} \Delta_{fj}x^j,$ $g(x) = g_1(x)d(x)/||g_1d||_2 + 10^{-8}\Delta_g(x)/||\Delta_g||_2, \ \Delta_g(x) = \sum_{j=0}^{10i} \Delta_{gj}x^j$



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Fake Common Roots (100 pairs of
$$(f,g)$$
 for each $i = 1, ..., 10$)
 $f=d \cdot \prod_{j=1}^{2i} (x-\omega_{f,j}) \prod_{j=1}^{2i} (x-\hat{\omega}_{f,j}), g=d \cdot \prod_{j=1}^{2i} (x-\omega_{g,j}) \prod_{j=1}^{2i} (x-\hat{\omega}_{g,j}),$
 $d = \prod_{j=1}^{3i} (x - \omega_{d,j}) \prod_{j=1}^{3i} (x - \hat{\omega}_{d,j}), \omega_{\cdot,j} = O(10^{-2}), \hat{\omega}_{\cdot,j} = O(10^2)$
where $\omega_{\cdot,j}, \hat{\omega}_{\cdot,j}$ are randomly chosen, $f(x), g(x)$ are normalized (i.e.
 $\|f(x)\|_2 = \|g(x)\|_2 = 1$) and rounded with *Digits* := 10. We computed
with tolerance 10^{-5} . Note that the degree of approximate GCD $\geq 6i$.

Sum of detected degrees The resulting perturbation

■ ExQRGCD is 39.8 times slower than QRGCD.

QRGCD failed 624 times and didn't meet the tolerance 119 times.

Fake Common Roots (100 pairs of
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 $f=d \cdot \prod_{j=1}^{2i} (x-\omega_{f,j}) \prod_{j=1}^{2i} (x-\hat{\omega}_{f,j}), g=d \cdot \prod_{j=1}^{2i} (x-\omega_{g,j}) \prod_{j=1}^{2i} (x-\hat{\omega}_{g,j}),$
 $d = \prod_{j=1}^{3i} (x-\omega_{d,j}) \prod_{j=1}^{3i} (x-\hat{\omega}_{d,j}), \omega_{\cdot,j} = O(10^{-2}), \hat{\omega}_{\cdot,j} = O(10^{2})$



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Numerical Experiments against Fastgcd/UVGCD

Examples in Bini and Boito (2007 and 2010)

- Mignotte-like polynomials (Ex 8.2.1 and 8.2.2 in Boito (2007)),
- An ill-conditioned case (Ex 8.4.1 in Boito (2007)),
- Other examples in Boito (2007), for real univariate polynomials.

The results

■ For Example 8.2.1, ExQRGCD is not better than Fastgcd but same as UVGCD.

For Example 8.2.2, ExQRGCD is almost better than others.

- For Example 8.4.1,
 - ExQRGCD is not good though it detected the correct degree.

For most of other examples,

ExQRGCD is not better than Fastgcd and UVGCD.

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Numerical Experiments against Fastgcd/UVGCD

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For most of other examples, ExQRGCD is not better than Fastgcd and UVGCD.

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Summary

The weak points of QRGCD and improvements in ExQRGCD

Absolute closeness and once detection in QRGCD are the issue.

Our contribution: relative closeness and conservative detection.

Numerical Experiments

• ExQRGCD is much better than QRGCD in the following points:

- Degree of detected approximate GCD: deg(d).
- Size of resulting perturbations: $\|\Delta_f\|_2$ and $\|\Delta_g\|_2$.

■ However, ExQRGCD still should be improved:

- ExQRGCD is slower than QRGCD.
- ExQRGCD is still not better than UVGCD and Fastgcd.

But there are polynomials for which ExQRGCD is better.

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Approximate GCD	QRGCD	ExQRGCD	Numerical Experiments	Summary
Summary				
		e annun y		
The weak poi	nts of QRGC	D and improve	ements in ExQRGCD	

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- Our contribution: relative closeness and conservative detection.

Numerical Experiments

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- However, ExQRGCD still should be improved:
 - ExQRGCD is slower than QRGCD.
 - ExQRGCD is still not better than UVGCD and Fastgcd.
 - But there are polynomials for which ExQRGCD is better.

Thanks for your attention!

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