Automatization and Non-Automatizability

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Outline

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- Non-Automatizability
 - Complexity Theory for "hard" problems
 - Resolution
 - Polynomial Calculus
- Connection between Resolution and Res(k)
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Motivation

Up to now: Lower bounds for propositional logic If there is a short proof, then we want to find it

Definition

A proof system *P* is (quasi-)automatizable if there is a deterministic algorithm which returns in (quasi-)polynomial time of the shortest *P*-proof of a tautology τ its *P*-proof.

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Definition

A proof system P is weakly automatizable if there is a proof system S that p-simulates P and is automatizable.

Approximation Algorithms

Definition

The approximation ratio ρ of an algorithm for an optimization problem is defined by

$$\rho := \max\left\{\frac{OPT(A)}{OPT}, \frac{OPT}{OPT(A)}\right\}.$$

An optimization problem has a polynomial time approximation scheme (PTAS), if there is an algorithm, which for every $\epsilon > 0$ computes, in time of at most $n^{O(\frac{1}{\epsilon})}$, an $(1 + \epsilon)$ -approximation.

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Definition

An optimization problem has an efficient polynomial time approximation scheme (EPTAS), if there is an algorithm, which for every $\epsilon > 0$ computes, in time of at most $f(\frac{1}{\epsilon})p(n)$, an $(1 + \epsilon)$ -approximation (*p* a polynomial, *f* computable).

Parametrized Complexity

Definition

 \mathcal{FPT} consists of all languages $L \subseteq \Sigma^* \times \mathbb{N}$ for which there exists an algorithm Φ , a constant *c* and a recursive function $f : \mathbb{N} \to \mathbb{N}$ such that:

- the running time of $\Phi(x, k)$ is at most $f(k)|x|^c$
- $(x,k) \in L$ iff $\Phi(x,k) = 1$

The class $\mathcal{W}[\mathcal{P}]$ contains all the problems which can be parametrized reduced to weighted circuit satisfiability: Input: A circuit *C* and an positive integer *k*. Question: Is there a satisfying assignment with *k* ones?

The problem monotone minimum circuit satisfying assignment (MMCSA) is an optimization problem with a circuit C with n variables as input as input.

Objective function: $\sigma(a)$ which returns the number of ones in an assignment $a \in \{0, 1\}$ such that C(a) = 1.

Definition

$$\sigma(C) = \min_{a \text{ is solution of MMCSA}} \sigma(a)$$

The class \mathcal{FPR} of parametrized problems consists of all languages $L \subseteq \Sigma^* \times \mathbb{N}$ for which there is a probabilistic algorithm Φ , a constant c and a recursive function $f : \mathbb{N} \to \mathbb{N}$ such that:

- $\Phi(x,k)$ runs in at most $f(k)|x|^c$
- if $(x,k) \in L$ then $Pr[\Phi(x,k)=1] \geq \frac{1}{2}$
- if $(x, k) \notin L$ then $Pr[\Phi(x, k) = 1] = 0$

Self Improvement

Lemma

For every fixed integer $d \ge 1$ there exists a polynomial time computable function π which maps monotone circuits into monotone circuits with $\sigma(\pi(C)) = \sigma(C)^d$ for all C.

Fact

$\mathcal{FPT}\subseteq \mathcal{FPR}$

$\mathcal{FPT}\subseteq\mathcal{W}[\mathcal{P}]$

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Fact

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Fact

The decision version of MMCSA is $\mathcal{W}[\mathcal{P}]$ -complete.

Fact

If a problem A has an EPTAS then A is in \mathcal{FPT} .

What do we want to show?

Goal

If Resolution or tree-like Resolution is automatizable, then $\mathcal{W}[\mathcal{P}] \subseteq \text{co-}\mathcal{FPR}.$

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If Resolution or tree-like Resolution is automatizable, then $\mathcal{W}[\mathcal{P}] \subseteq \text{co-}\mathcal{FPR}.$

Roadmap

- 1. Create a PTAS
- 2. Get rid of the exponent

There exists a polynomial time computable function τ which maps any pair $(C, 1^m)$, with a monotone circuit C and an integer m, to an unsatisfiable CNF $\tau(C, m)$ such that:

$$S_T(\tau(C,m)) \leq |C| m^{O(\min\{\sigma(C),\log m\})}$$

and

$$S(\tau(C,m)) \geq m^{O(\min\{\sigma(C),\log m\})}.$$

If Resolution or tree-like Resolution is automatizable then there exists an constant h > 1 and an algorithm Φ working on pairs (C, k), where C is a monotone circuit and k is an integer such that:

- the running time of $\Phi(C, k)$ is at most $\exp(O(k^2))|C|^{O(1)}$
- if $\sigma(C) \leq k$ then $\Phi(C, k) = 1$
- if $\sigma(C) \ge hk$ then $\Phi(C, k) = 0$.

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Proof.

 $r := 2^{h \max\{k, \frac{\log|C|}{k}\}}$

S(C, r): build CNF, simulate refutation, stop after $(r^k|C|)^{h_0}$ steps if $S(C, r) \ge (|C|r^k)^{h_1}$ return 1 otherwise 0

If Resolution or tree-like Resolution is automatizable then for any fixed $\epsilon > 0$ there exists an algorithm Φ receiving as input a monotone circuit C which runs in time $\exp(\sigma(C)^{O(1)})|C|^{O(1)}$ and approximates $\sigma(C)$ within a factor $1 + \epsilon$.

If Resolution or tree-like Resolution is automatizable then for any fixed $\epsilon > 0$ there exists an algorithm Φ receiving as input a monotone circuit C which runs in time $\exp(\sigma(C)^{O(1)})|C|^{O(1)}$ and approximates $\sigma(C)$ within a factor $1 + \epsilon$.

Proof.

From the last lemma we can construct an approximation algorithm with approximation ratio *h*: Compute $\Phi(C, 1) \dots \Phi(C, l)$ while $\Phi(C, l) \neq 0$ and return *l* if $\Phi(C, l) = 0$

If Resolution or tree-like Resolution is automatizable then $\mathcal{W}[\mathcal{P}] \subseteq co-\mathcal{FPR}.$

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Proof.

Construct a (randomized) circuit $\beta(C, k)$ and $\alpha(k)$ in polynomial time:

$$\sigma(C) \le k \Rightarrow \Pr[\sigma(\beta(C,k)) \le \alpha(k)] = 1$$

$$\sigma(C) \ge k + 1 \Rightarrow \Pr[\sigma(\beta(C,k)) \ge 2\alpha(k)] \ge \frac{1}{2}$$

Fact

$P[A \text{ set of } s \text{ circuits has less or equal than } sn - a \text{ input circuits}] \le N^k \left(\frac{4s^2n^2}{N}\right)^a$

$$P[\beta(C, N, d) \text{ is bad}] \le \sum_{i=1}^{d-1} N^{k_{i+1}} \left(\frac{4k_{i+1}^2 n^2}{N}\right)^{k_{i+1}\sqrt{k}}$$
$$= \sum_{i=1}^{d-1} \left(\frac{4k_{i+1}^2}{n^{1-3/\sqrt{k}}}\right)^{k_{i+1}\sqrt{k}} \le \sum_{i=1}^{d-1} \left(\frac{1}{3}\right)^{k_{i+1}\sqrt{k}} \le \frac{1}{2}$$

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Polynomial Calculus

- There is an algorithm which works in cubic time of the size of the dense representation.
- Shown results hold for PC, too.

Want to show: Resolution is weakly automatizable iff Res(2) has feasible interpolation.

Definition

The variable $z_{l_1,...,l_s}$ of variables $l_1,...,l_s$ is constituted by its defining clauses:

$$\neg z_{l_1,\ldots,l_s} \lor l_i \quad \forall i \in [s]$$
$$z_{l_1,\ldots,l_s} \lor \neg l_1 \lor \cdots \land \neg l_s$$

It can be interpreted as $l_1 \wedge \cdots \wedge l_s$.

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Definition

The set C_k of a set of clauses C is the union of C with all the defining clauses for the variables $z_{l_1,...,l_s}$.

If the set of clauses C has a Res(k) refutation of size S, then C_k has a Resolution refutation of size O(kS). If the Res(k) refutation is tree-like, then the Resolution refutation is also tree-like.

The set REF(S) is the set of pairs (C, m) with an CNF formula C that has an S-refutation with size m.

The set SAT^* contains the pairs (C, m) such that C is a satisfiable CNF formula.

 $(REF(S), SAT^*)$ is called the canonical pair of S.

A canonical pair is separable if there is an algorithm running in polynomial time and returns *false* on every input from REF(S) and *true* if (C, m) is in SAT^* .

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Reflection Principle

Definition

A CNF formula which is true iff

- z encodes a truth assignment of a CNF x
- x is of size r and uses n variables

is called $SAT_n^r(x, z)$.

Let us call a CNF $REF_{r,m}^{n}(x, y)$ if it evaluates to true iff

- y encodes an S-refutation of a CNF x
- the size of the refutation is m
- x is of size r and uses n variables

The collection of the CNFs $REF_{r,m}^n(y,z) \wedge SAT_r^n(x,z)$ is the Reflection Principle of *S*.

A proof system *S* has the interpolation property in time T = T(m) if there is an algorithm which runs in time *T* and decides for an contradictory CNF $B := A_0(x, y_0) \land A_1(x, y_1) (x, y_0, y_1 \text{ are disjoint sets})$ if $A_0(x, y_0)$ or $A_1(x, y_1)$ is contradictory where *m* is the minimal size of an refutation of *B*. If T(m) is polynomial in *m* then *S* has feasible interpolation.

Theorem (Pudlak)

If the reflection principle of S has polynomial sized refutations in a proof system that has feasible interpolation, then the canonical pair for S is separable in polynomial time.

The Reflection Principle for Resolution $SAT_r^n(x, z) \wedge REF_{r,m}^n(x, y)$ has Res(2) refutations of size $(nr + nm)^{O(1)}$.

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Lemma

If Res(2) has feasible interpolation, then Resolution is weakly automatizable.

Corollary (Pudlak)

The canonical pair of a proof system S is separable in polynomial time iff S is weakly automatizable.

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The canonical pair of a proof system S is separable in polynomial time iff S is weakly automatizable.

Theorem

If Resolution is weakly automatizable, then Res(2) has feasible interpolation.



Thank you for your attention.

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