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Setting:

We assume an LP of the form

$$\begin{array}{cccc}
\min & c^T x \\
\text{s.t.} & Ax & \geq & b \\
& & x & \geq & 0
\end{array}$$

We assume that the LP is bounded.

Ensuring Conditions

Given a standard minimization LP

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how can we obtain an LP of the required form?

► Compute a lower bound on $c^T x$ for any basic feasible solution.

Let s denote the smallest common multiple of all denominators of entries in A, b.

Multiply entries in A,b by s to obtain integral entries. This does not change the feasible region.

Add slack variables to A; denote the resulting matrix with $ar{A}$.

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Theorem 2 (Cramers Rule)

Let M be a matrix with $\det(M) \neq 0$. Then the solution to the system Mx = b is given by

$$x_i = \frac{\det(M_j)}{\det(M)}$$
 ,

where M_i is the matrix obtained from M by replacing the i-th column by the vector b.

Define

$$X_i = \begin{pmatrix} | & | & | & | \\ e_1 \cdots e_{i-1} & \mathbf{x} & e_{i+1} \cdots e_n \\ | & | & | & | \end{pmatrix}$$

Note that expanding along the *i*-th column gives that $det(X_i) = x_i$.

Further, we have

$$MX_{j} = \begin{pmatrix} | & | & | & | & | \\ Me_{1} \cdots Me_{i-1} Mx Me_{i+1} \cdots Me_{n} \\ | & | & | & | \end{pmatrix} = M$$

► Hence,

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Hence,

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Let Z be the maximum absolute entry occuring in \bar{A}, \bar{b} or c. Let C denote the matrix obtained from \bar{A}_B by replacing the j-th column with vector \bar{b} (for some j).

Observe that

|det(*C*)|

Here $\mathrm{sgn}(\pi)$ denotes the sign of the permutation, which is 1 if the permutation can be generated by an even number of transpositions (exchanging two elements), and -1 if the number of transpositions is odd.

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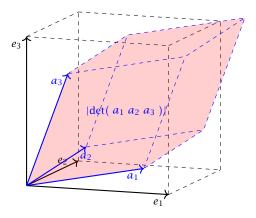
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$$\le m^{m/2}Z^m.$$

Hadamards Inequality



Hadamards inequality says that the volume of the red parallelepiped (Spat) is smaller than the volume in the black cube (if $||e_1|| = ||a_1||$, $||e_2|| = ||a_2||$, $||e_3|| = ||a_3||$).

Ensuring Conditions

Given a standard minimization LP

$$\begin{array}{cccc}
\min & c^T x \\
\text{s.t.} & Ax & \geq & b \\
& x & \geq & 0
\end{array}$$

how can we obtain an LP of the required form?

▶ Compute a lower bound on c^Tx for any basic feasible solution. Add the constraint $c^Tx \ge -mZ(m! \cdot Z^m) - 1$. Note that this constraint is superfluous unless the LP is unbounded.

Ensuring Conditions

Compute an optimum basis for the new LP.

- ▶ If the cost is $c^T x = -(mZ)(m! \cdot Z^m) 1$ we know that the original LP is unbounded.
- Otw. we have an optimum basis.

We give a routine SeidelLP(\mathcal{H},d) that is given a set \mathcal{H} of explicit, non-degenerate constraints over d variables, and minimizes c^Tx over all feasible points.

In addition it obeys the implicit constraint $c^T x \ge -(mZ)(m! \cdot Z^m) - 1$.

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9: solve $a_h^T x = b_h$ for some variable x_ℓ ; 10: eliminate x_{ℓ} in constraints from $\hat{\mathcal{H}}$ and in implicit constr.;

add the value of x_{ℓ} to \hat{x}^* and return the solution









Note that for the case d=1, the asymptotic bound $\mathcal{O}(\max\{m,1\})$ is valid also for the case m=0.

- ▶ If d = 1 we can solve the 1-dimensional problem in time $O(\max\{m, 1\})$.
- ▶ If d > 1 and m = 0 we take time O(d) to return d-dimensional vector x.
- ▶ The first recursive call takes time T(m-1,d) for the call plus O(d) for checking whether the solution fulfills h.
- If we are unlucky and \hat{x}^* does not fulfill h we need time $\mathcal{O}(d(m+1)) = \mathcal{O}(dm)$ to eliminate x_ℓ . Then we make a recursive call that takes time T(m-1,d-1).
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This gives the recurrence

$$T(m,d) = \begin{cases} \mathcal{O}(\max\{1,m\}) & \text{if } d=1\\ \mathcal{O}(d) & \text{if } d>1 \text{ and } m=0\\ \mathcal{O}(d) + T(m-1,d) +\\ \frac{d}{m}(\mathcal{O}(dm) + T(m-1,d-1)) & \text{otw.} \end{cases}$$

Note that T(m, d) denotes the expected running time.

Let C be the largest constant in the \mathcal{O} -notations.

$$T(m,d) = \begin{cases} C \max\{1,m\} & \text{if } d = 1 \\ Cd & \text{if } d > 1 \text{ and } m = 0 \\ Cd + T(m-1,d) + \\ \frac{d}{m}(Cdm + T(m-1,d-1)) & \text{otw.} \end{cases}$$

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We show $T(m, d) \le Cf(d) \max\{1, m\}$.

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 $T(m,1) \le C \max\{1,m\} \le Cf(1) \max\{1,m\} \text{ for } f(1) \ge 1$

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$$d>1; m=0:$$

$$T(0,d) \leq \mathcal{O}(d)$$

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$$T(0,d) \le \mathcal{O}(d) \le Cd \le Cf(d) \max\{1,m\} \text{ for } f(d) \ge d$$

d > 1; m = 1:

$$T(1,d) = \mathcal{O}(d) + T(0,d) + d\Big(\mathcal{O}(d) + T(0,d-1)\Big)$$

$$\leq Cd + Cd + Cd^2 + dCf(d-1)$$

$$\leq Cf(d) \max\{1, m\} \text{ for } f(d) \geq 3d^2 + df(d-1)$$

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d > 1; m > 1:
(by induction hypothesis statm. true for d' < d, m' \ge 0; and for d' = d, m' < m)
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$$\leq 2Cd^2 + Cf(d)(m-1) + dCf(d-1)$$

d > 1: m > 1:

$$\begin{split} T(m,d) &= \mathcal{O}(d) + T(m-1,d) + \frac{d}{m} \Big(\mathcal{O}(dm) + T(m-1,d-1) \Big) \\ &\leq Cd + Cf(d)(m-1) + Cd^2 + \frac{d}{m} Cf(d-1)(m-1) \\ &\leq 2Cd^2 + Cf(d)(m-1) + dCf(d-1) \\ &\leq Cf(d)m \end{split}$$

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if
$$f(d) \ge df(d-1) + 2d^2$$
.

▶ Define $f(1) = 3 \cdot 1^2$ and $f(d) = df(d-1) + 3d^2$ for d > 1.

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$$\begin{split} f(d) &= 3d^2 + df(d-1) \\ &= 3d^2 + d\left[3(d-1)^2 + (d-1)f(d-2)\right] \\ &= 3d^2 + d\left[3(d-1)^2 + (d-1)\left[3(d-2)^2 + (d-2)f(d-3)\right]\right] \\ &= 3d^2 + 3d(d-1)^2 + 3d(d-1)(d-2)^2 + \dots \\ &\quad + 3d(d-1)(d-2) \cdot \dots \cdot 4 \cdot 3 \cdot 2 \cdot 1^2 \\ &= 3d! \left(\frac{d^2}{d!} + \frac{(d-1)^2}{(d-1)!} + \frac{(d-2)^2}{(d-2)!} + \dots\right) \end{split}$$

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$$= \mathcal{O}(d!)$$

since $\sum_{i\geq 1} \frac{i^2}{i!}$ is a constant.

$$\sum_{i \ge 1} \frac{i^2}{i!} = \sum_{i \ge 0} \frac{i+1}{i!} = e + \sum_{i \ge 1} \frac{i}{i!} = 2e$$