

04 – Treaps



The dictionary problem

Given: Universe $(U, <)$ of keys with a total order

Goal: Maintain set $S \subseteq U$ under the following operations

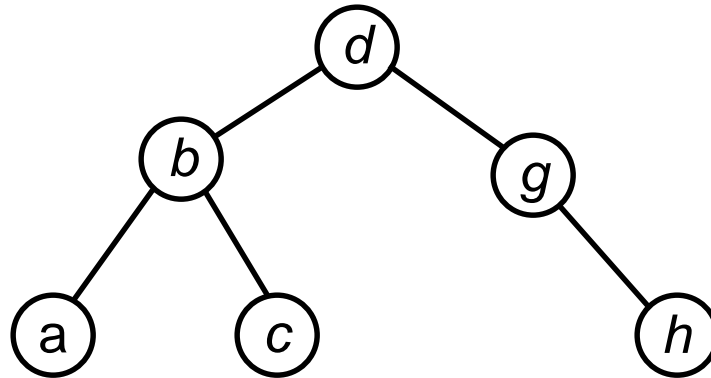
- **Search** (x, S) : Is $x \in S$?
- **Insert** (x, S) : Insert x into S if not already in S .
- **Delete** (x, S) : Delete x from S .

Extended set of operations

- **Minimum(S):** Return smallest key.
- **Maximum(S):** Return largest key.
- **List(S):** Output elements of S in increasing order of key.
- **Union(S_1, S_2):** Merge S_1 and S_2 .
Condition: $\forall x_1 \in S_1, x_2 \in S_2: x_1 < x_2$
- **Split(S, x, S_1, S_2):** Split S into S_1 and S_2 .
 $\forall x_1 \in S_1, x_2 \in S_2: x_1 \leq x$ and $x < x_2$

Known solutions

- **Binary search trees**



Drawback: Sequence of insertions may lead to a linear list a, b, c, d, e, f

- **Height balanced trees:** AVL trees, (a,b)-trees

Drawback: Complex algorithms or high memory requirements.

If n elements are inserted in random order into a binary search tree, the expected depth is $1.39 \log n$.

Idea: Each element x is assigned a priority chosen uniformly at random

$$\text{prio}(x) \in \mathbb{R}$$

The goal is to establish the following property.

(*) The search tree has the structure that would result if elements were inserted in the order of their priorities.

Treaps (Tree + Heap)

Definition: A treap is a binary tree.

Each node contains one element x with $\text{key}(x) \in U$ and $\text{prio}(x) \in \mathbb{R}$.

The following properties hold.

- **Search tree property**

For each element x :

- elements y in the left subtree of x satisfy: $\text{key}(y) < \text{key}(x)$
- elements y in the right subtree of x satisfy : $\text{key}(y) > \text{key}(x)$

- **Heap property**

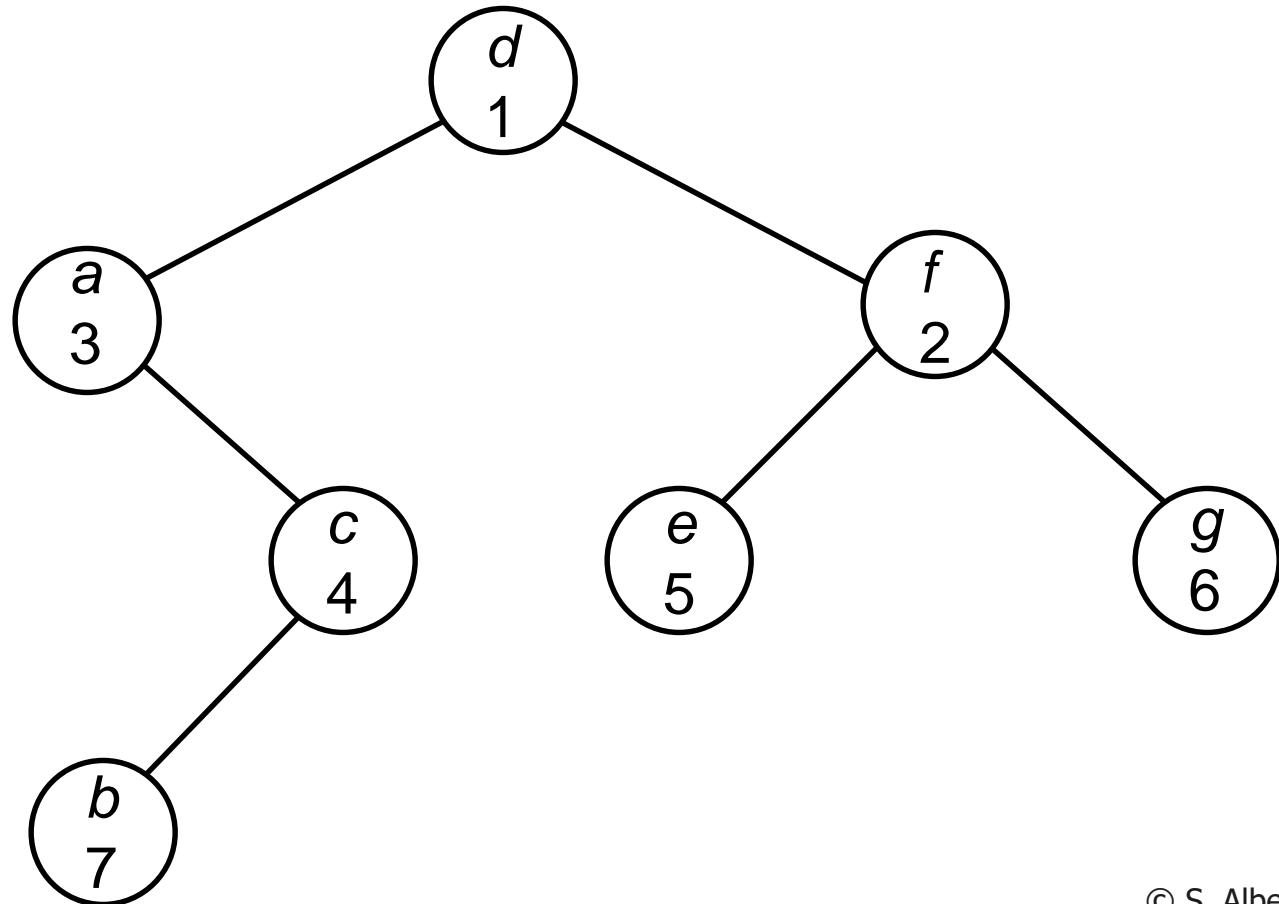
For all elements x, y :

If y is a child of x , then $\text{prio}(y) > \text{prio}(x)$.

All priorities are pairwise distinct.

Example

| key | <i>a</i> | <i>b</i> | <i>c</i> | <i>d</i> | <i>e</i> | <i>f</i> | <i>g</i> |
|----------|----------|----------|----------|----------|----------|----------|----------|
| priority | 3 | 7 | 4 | 1 | 5 | 2 | 6 |



Treap uniqueness

Lemma: For elements x_1, \dots, x_n with $\text{key}(x_i)$ and $\text{prio}(x_i)$, there exists a unique treap. It satisfies property (*).

Proof:

$n=1$: obvious

Suppose that lemma holds for element sets up to cardinality $n-1$.

$n-1 \Rightarrow n$: The element x_i with smallest priority among x_1, \dots, x_n must be in the root.

Elements x_j with $\text{key}(x_j) < \text{key}(x_i)$ are in the left subtree of x_i .

Elements x_j with $\text{key}(x_j) > \text{key}(x_i)$ are in the right subtree of x_i .

By induction hypothesis there exists a unique treap for the elements in the left/right subtrees of x_i .

Hence there exists a unique treap for x_1, \dots, x_n .

Treap uniqueness

If the elements are inserted in order of increasing priority, then element x_i with smallest priority is inserted first and resides in the root.

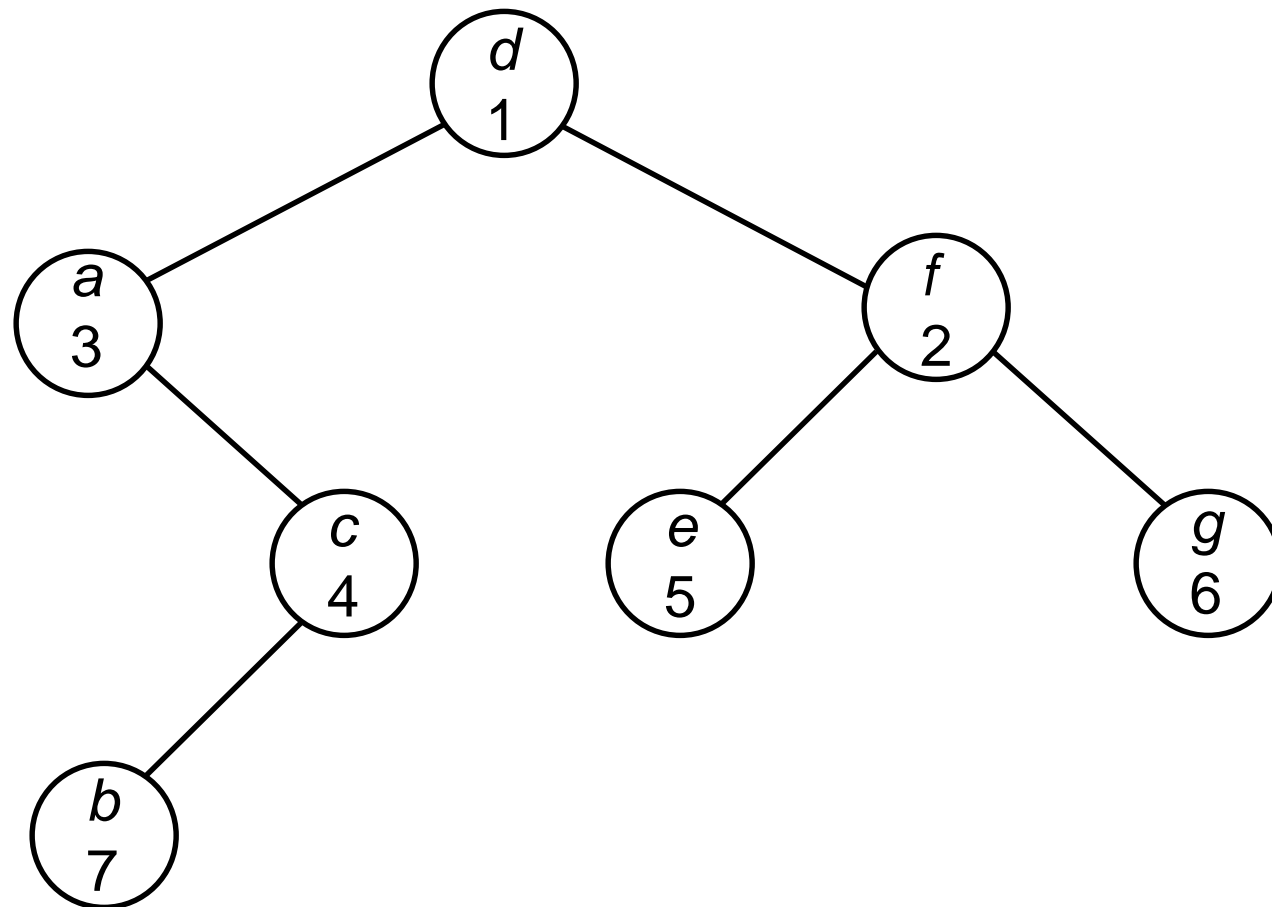
Elements x_j with $\text{key}(x_j) < \text{key}(x_i)$ are in the left subtree of x_i .

Elements x_j with $\text{key}(x_j) > \text{key}(x_i)$ are in the right subtree of x_i .

By induction hypothesis the treaps in the left/right subtrees of x_i have the same structure as if the respective elements were inserted in order of increasing priorities.

Hence property (*) holds.

Search for an element



Search for element with key k

```
1   $v := \text{root};$ 
2  while  $v \neq \text{nil}$  do
3      case  $\text{key}(v) = k$  : stop; “element found” (successful search)
4           $\text{key}(v) < k$  :  $v := \text{RightChild}(v);$ 
5           $\text{key}(v) > k$  :  $v := \text{LeftChild}(v);$ 
6      endcase;
7  endwhile;
8  “element not found” (unsuccessful search)
```

Running time: $O(\# \text{ elements on the search path})$

Analysis of the search path

Elements x_1, \dots, x_n x_i has i -th smallest key

Let M be a subset of the elements.

$P_{\min}(M)$ = element in M with lowest priority

Lemma:

a) Let $i < m$. x_i is ancestor of x_m iff $P_{\min}(\{x_i, \dots, x_m\}) = x_i$

b) Let $m < i$. x_i is ancestor of x_m iff $P_{\min}(\{x_m, \dots, x_i\}) = x_i$

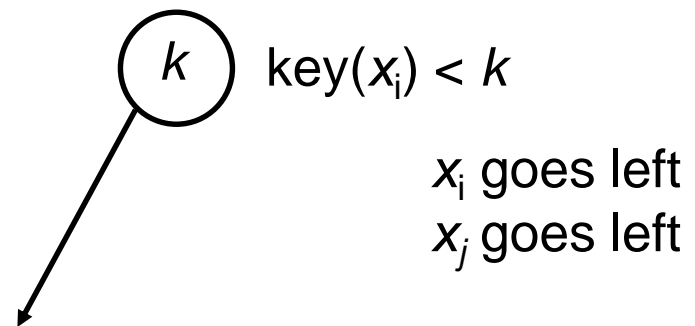
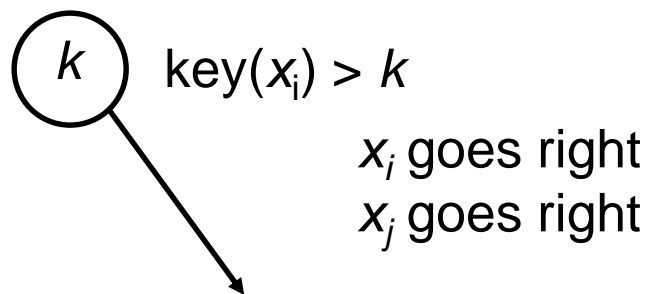
Analysis of the search path

Proof: a) Use (*). Elements are inserted in order of increasing priorities.

“ \Leftarrow ” $P_{\min}(\{x_i, \dots, x_m\}) = x_i \Rightarrow x_i$ is inserted first among $\{x_i, \dots, x_m\}$.

When x_i is inserted, the tree contains only keys k with
 $k < \text{key}(x_i)$ or $k > \text{key}(x_m)$

When x_j , with $i < j \leq m$, is inserted, it traverses the same search path as x_i . Hence x_j becomes a descendent of x_i .



Analysis of the search path

Proof: a) (Let $i < m$. x_i is ancestor of x_m iff $P_{\min}(\{x_i, \dots, x_m\}) = x_i$)

“ \Rightarrow ” Let $x_j = P_{\min}(\{x_i, \dots, x_m\})$. Show: $x_i = x_j$

Suppose: $x_i \neq x_j$

When x_j is inserted, the tree contains only keys k with

$k < \text{key}(x_j)$ or $k > \text{key}(x_m)$

All elements of $\{x_i, \dots, x_m\} \setminus \{x_j\}$ traverse the same search path as x_j :

Node with key $k < \text{key}(x_j)$: All elements from $\{x_i, \dots, x_m\}$ turn left.

Node with key $k > \text{key}(x_m)$: All elements from $\{x_i, \dots, x_m\}$ turn right.

Hence all elements of $\{x_i, \dots, x_m\} \setminus \{x_j\}$ become descendants of x_j .

Case 1: $x_j = x_m$ x_i is descendent of x_m Contradiction!

Case 2: $x_j \neq x_m$ x_i and x_m are in different subtrees of x_j Contradiction!

Part b) can be shown analogously.

Analysis of the 'Search' operation

Let T be a treap with elements x_1, \dots, x_n x_i has i -th smallest key

n -th Harmonic number:

$$H_n = \sum_{k=1}^n 1/k$$

Lemma:

1. **Successful search:** The expected number of nodes on the path to x_m is $H_m + H_{n-m+1} - 1$.
2. **Unsuccessful search :** Let m be the number of keys that are smaller than the search key k . The expected number of nodes on the search path is $H_m + H_{n-m}$.

Analysis of the 'Search' operation

Proof: Part 1

$$X_{m,i} = \begin{cases} 1 & x_i \text{ is ancestor of } x_m \\ 0 & \text{otherwise} \end{cases}$$

$X_m = \#$ nodes on the path from the root to x_m (incl. x_m)

$$X_m = 1 + \sum_{i < m} X_{m,i} + \sum_{i > m} X_{m,i}$$

$$E[X_m] = 1 + E\left[\sum_{i < m} X_{m,i}\right] + E\left[\sum_{i > m} X_{m,i}\right]$$

Analysis of the 'Search' operation

$i < m$:

$$E[X_{m,i}] = \text{Prob}[x_i \text{ is ancestor of } x_m] = 1/(m - i + 1)$$

All elements in $\{x_i, \dots, x_m\}$ have the same probability of being the one with the smallest priority.

$$\text{Prob}[P_{\min}(\{x_i, \dots, x_m\}) = x_i] = 1/(m - i + 1)$$

$i > m$:

$$E[X_{m,i}] = 1/(i - m + 1)$$

Analysis of the 'Search' operation

$$\begin{aligned} E[X_m] &= 1 + \sum_{i < m} \frac{1}{m - i + 1} + \sum_{i > m} \frac{1}{i - m + 1} \\ &= 1 + \frac{1}{m} + \dots + \frac{1}{2} + \frac{1}{2} + \dots + \frac{1}{n - m + 1} \\ &= H_m + H_{n-m+1} - 1 \end{aligned}$$

Analysis of the 'Search' operation

Part 2

$m = 0$: Search path is the same as that for x_1 . By Part 1, the expected number of nodes on the search path is $H_1 + H_n - 1 = H_n$.

$m = n$: Search path is the same as that for x_n . By Part 1, the expected number of nodes on the search path is $H_n + H_1 - 1 = H_n$.

$0 < m < n$: x_m is an ancestor of x_{m+1} or vice versa. When searching for k , at every

x_i with $i < m$, the search path turns right

x_i with $i > m+1$, the search path turns left.

Hence the **search path for k** is the same as that for x_m, x_{m+1} until **one of the two keys are hit**.

Analysis of the 'Search' operation

If x_m is hit first, the remaining search path of k is identical to that of x_{m+1} .

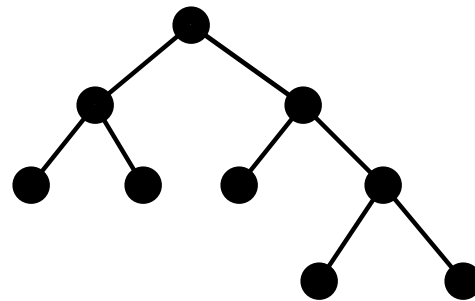
If x_{m+1} is hit first, the remaining search path of k is identical to that of x_m .



Hence the length of the search path is upper bounded by that of x_m and x_{m+1} , i.e. $\max \{H_m + H_{n-m+1} - 1, H_{m+1} + H_{n-m} - 1\} \leq H_m + H_{n-m}$.

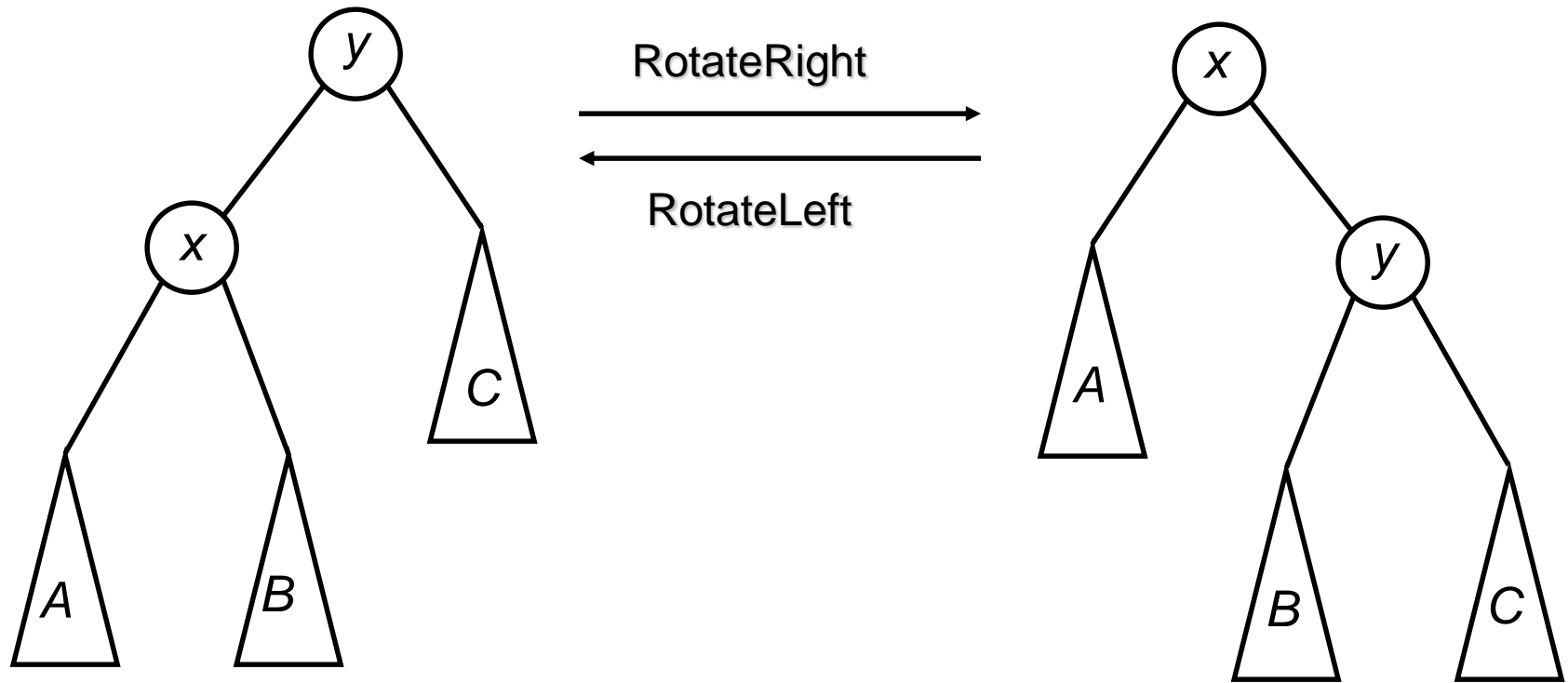
Inserting a new element x

1. Choose $\text{prio}(x)$.
2. Search for the **position** of x in the tree.



3. Insert x as a leaf.
4. Restore the **heap property**.
while $\text{prio}(\text{parent}(x)) > \text{prio}(x)$ **do**
 if x is left child **then** $\text{RotateRight}(\text{parent}(x))$
 else $\text{RotateLeft}(\text{parent}(x));$
endif
endwhile;

Rotations

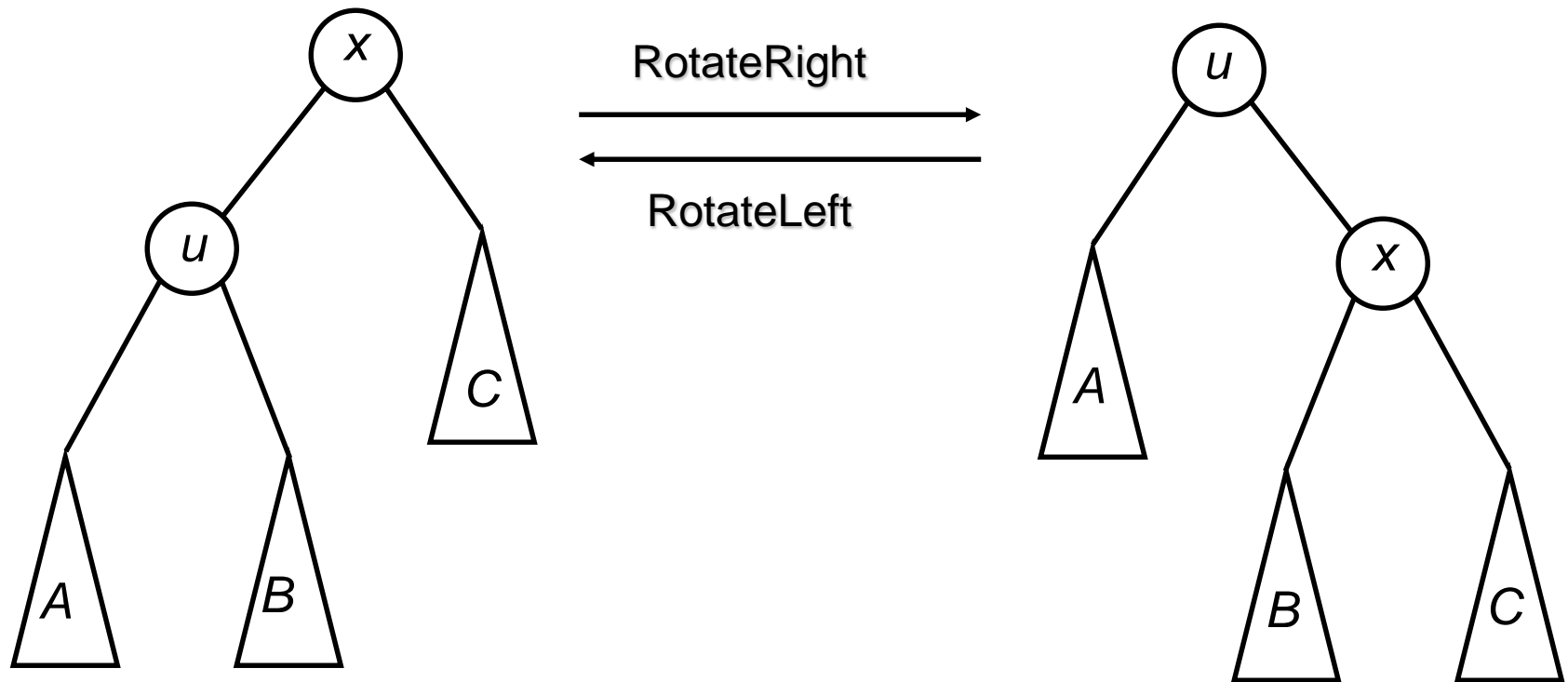


The rotations maintain the search tree property and restore the heap property.

Deleting an element x

1. Find x in the tree.
2. **while** x is not a leaf **do**
 - $u :=$ child with smaller priority;
 - if** u is left child **then** RotateRight(x)
 - else** RotateLeft(x);
 - endif;****endwhile;**
3. Delete x ;

Rotations



Analysis of 'Insert' and 'Delete' operations

Lemma: The expected running time of insert and delete operations is $O(\log n)$. The expected number of rotations is 2.

Proof: Analysis of insert (delete is the inverse operation)

rotations = depth of x after being inserted as a leaf (1)

- depth of x after the rotations (2)

Let $x = x_m$.

(2) Expected depth is $H_m + H_{n-m+1} - 1$.

(1) Expected depth is $H_{m-1} + H_{n-m} + 1$.

The tree contains $n-1$ elements, $m-1$ of them being smaller.

$$\# \text{ rotations} = H_{m-1} + H_{n-m} + 1 - (H_m + H_{n-m+1} - 1) < 2$$

Extended set of operations

n = number of elements in treap T .

- **Minimum(T):** Return the smallest key. $O(\log n)$
- **Maximum(T):** Return the largest key. $O(\log n)$
- **List(T):** Output elements of S in increasing order. $O(n)$

- **Union(T_1, T_2):** Merge T_1 and T_2 .
Condition: $\forall x_1 \in T_1, x_2 \in T_2: \text{key}(x_1) < \text{key}(x_2)$
- **Split(T, k, T_1, T_2):** Split T into T_1 and T_2 .
 $\forall x_1 \in T_1, x_2 \in T_2: \text{key}(x_1) \leq k$ and $k < \text{key}(x_2)$

The 'Split' operation

$\text{Split}(T, k, T_1, T_2)$: Split T into T_1 and T_2 .

$$\forall x_1 \in T_1, x_2 \in T_2: \text{key}(x_1) \leq k \text{ and } \text{key}(x_2) > k$$

W.l.o.g. key k is not in T .

Otherwise delete the element with key k and re-insert it into T_1 after the split operation.

1. Generate a new element x with $\text{key}(x)=k$ and $\text{prio}(x) = -\infty$.
2. Insert x into T .
3. Delete the new root. The left subtree is T_1 , the right subtree is T_2 .

The 'Union' operation

$\text{Union}(T_1, T_2)$: Merge T_1 and T_2 .

Condition: $\forall x_1 \in T_1, x_2 \in T_2: \text{key}(x_1) < \text{key}(x_2)$

1. Determine key k with $\text{key}(x_1) < k < \text{key}(x_2)$
for all $x_1 \in T_1$ and $x_2 \in T_2$.
2. Generate element x with $\text{key}(x)=k$ and $\text{prio}(x) = -\infty$.
3. Generate treap T with root x , left subtree T_1 and
right subtree T_2 .
4. Delete x from T .

Lemma: The expected running time of the operations **Union** and **Split** is $O(\log n)$.

Implementation

Priorities from $[0,1)$

Priorities are used only when two elements are compared to find out which of them has the higher priority.

In case of equality, extend both priorities by bits chosen uniformly at random until two corresponding bits differ.

$$p_1 = 0.010111001$$

$$p_2 = 0.010111001$$

$$p_1 = 0.010111001\mathbf{011}$$

$$p_2 = 0.010111001\mathbf{010}$$