#### How to choose augmenting paths?

- We need to find paths efficiently.
- We want to guarantee a small number of iterations.

### Several possibilities:

- Choose path with maximum bottleneck capacity.
- Choose path with sufficiently large bottleneck capacity.
- Choose the shortest augmenting path.

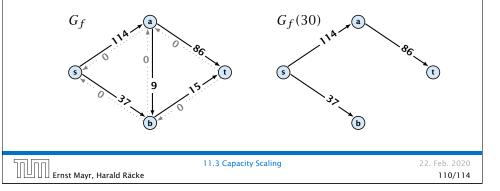
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	<b>Algorithm 1</b> maxflow( $G, s, t, c$ ) 1: <b>foreach</b> $e \in E$ <b>do</b> $f_e \leftarrow 0$ ; 2: $\Delta \leftarrow 2^{\lceil \log_2 C \rceil}$ 3: <b>while</b> $\Delta \ge 1$ <b>do</b> 4: $G_f(\Delta) \leftarrow \Delta$ -residual graph 5: <b>while</b> there is augmenting path $P$ in $G_f(\Delta)$ <b>do</b> 6: $f \leftarrow augment(f, c, P)$ 7: $update(G_f(\Delta))$ 8: $\Delta \leftarrow \Delta/2$ 9: <b>return</b> $f$	-
	9: return J	
Ernst M	11.3 Capacity Scaling ayr, Harald Räcke	22. Feb. 111

## **Capacity Scaling**

## Intuition:

- Choosing a path with the highest bottleneck increases the flow as much as possible in a single step.
- Don't worry about finding the exact bottleneck.
- Maintain scaling parameter  $\Delta$ .
- $G_f(\Delta)$  is a sub-graph of the residual graph  $G_f$  that contains only edges with capacity at least  $\Delta$ .



# Capacity Scaling

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#### Assumption:

All capacities are integers between 1 and C.

#### Invariant:

All flows and capacities are/remain integral throughout the algorithm.

### Correctness:

The algorithm computes a maxflow:

- because of integrality we have  $G_f(1) = G_f$
- therefore after the last phase there are no augmenting paths anymore
- this means we have a maximum flow.

## **Capacity Scaling**

**Lemma 5** *There are*  $\lceil \log C \rceil + 1$  *iterations over*  $\Delta$ *.* **Proof:** obvious.

## Lemma 6

Let f be the flow at the end of a  $\Delta$ -phase. Then the maximum flow is smaller than  $val(f) + m\Delta$ .

**Proof:** less obvious, but simple:

- There must exist an *s*-*t* cut in  $G_f(\Delta)$  of zero capacity.
- In  $G_f$  this cut can have capacity at most  $m\Delta$ .
- This gives me an upper bound on the flow that I can still add.

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# **Capacity Scaling**

### Lemma 7

There are at most 2m augmentations per scaling-phase.

### Proof:

- Let *f* be the flow at the end of the previous phase.
- ►  $\operatorname{val}(f^*) \leq \operatorname{val}(f) + 2m\Delta$
- Each augmentation increases flow by  $\Delta$ .

## **Theorem 8**

We need  $O(m \log C)$  augmentations. The algorithm can be implemented in time  $O(m^2 \log C)$ .

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