

04 – Treaps



Given: Universe (U, <) of keys with a total order

Goal: Maintain set $S \subseteq U$ under the following operations

- Search(x, S): Is $x \in S$?
- Insert(x,S): Insert x into S if not already in S.
- Delete(x, S): Delete x from S.



- Minimum(S): Return smallest key.
- Maximum(S): Return largest key.
- List(*S*):
- Union (S_1, S_2) :

Output elements of S in increasing order of key.

Merge S_1 and S_2 .

Condition: $\forall x_1 \in S_1$, $x_2 \in S_2$: $x_1 < x_2$

• Split(S, x, S_1, S_2): Split S into S_1 and S_2 .

 $\forall x_1 \in S_1$, $x_2 \in S_2$: $x_1 \leq x$ and $x < x_2$

Known solutions



• Binary search trees



Drawback: Sequence of insertions may lead to a linear list *a*, *b*, *c*, *d*, *e*, *f*

• Height balanced trees: AVL trees, (a,b)-trees Drawback: Complex algorithms or high memory requirements. If *n* elements are inserted in random order into a binary search tree, the expected depth is $1.39 \log n$.

Idea: Each element x is assigned a priority chosen uniformly at random $prio(x) \in \mathbb{R}$

The goal is to establish the following property.

(*) The search tree has the structure that would result if elements were inserted in the order of their priorities.

Definition: A treap is a binary tree. Each node contains one element *x* with $key(x) \in U$ and $prio(x) \in \mathbb{R}$. The following properties hold.

Search tree property

For each element x:

- elements y in the left subtree of x satisfy: key(y) < key(x)
- elements y in the right subtree of x satisfy : key(y) > key(x)

Heap property

For all elements x, y: If y is a child of x, then prio(y) > prio(x). All priorities are pairwise distinct.

Example







Lemma: For elements $x_1, ..., x_n$ with key (x_i) and prio (x_i) , there exists a unique treap. It satisfies property (*).

Proof:

n=1: obvious

Suppose that lemma holds for element sets up to cardinality *n*-1.

- $n-1 \Rightarrow n$: The element x_i with smallest priority among x_1, \dots, x_n must be in the root.
 - Elements x_i with $\text{key}(x_i) < \text{key}(x_i)$ are in the left subtree of x_i .
 - Elements x_i with $\text{key}(x_i) > \text{key}(x_i)$ are in the right subtree of x_i .
 - By induction hypothesis there exists a unique treap for the elements in the left/right subtrees of x_i .
 - Hence there exists a unique treap for x_1, \ldots, x_n .



If the elements are inserted in order of increasing priority, then element x_i with smallest priority is inserted first and resides in the root. Elements x_j with $\text{key}(x_j) < \text{key}(x_i)$ are in the left subtree of x_i . Elements x_j with $\text{key}(x_j) > \text{key}(x_i)$ are in the right subtree of x_i .

By induction hypothesis the treaps in the left/right subtrees of x_i have the same structure as if the respective elements were inserted in order of increasing priorities.

Hence property (*) holds.







- 1 v := root;
- 2 while $v \neq$ nil do
- 3 **case** key(v) = k: stop; "element found" (successful search)
- 4 key(v) < k : v := RightChild(v);

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$$\operatorname{key}(v) > k : v := \operatorname{LeftChild}(v);$$

- 6 endcase;
- 7 endwhile;
- 8 "element not found" (unsuccessful search)

Running time: O(# elements on the search path)

Elements x_1, \ldots, x_n x_i has *i*-th smallest key

Let *M* be a subset of the elements.

 $P_{min}(M)$ = element in *M* with lowest priority

Lemma:

- a) Let *i*<*m*. x_i is ancestor of x_m iff $P_{min}(\{x_i, ..., x_m\}) = x_i$
- b) Let m < i. x_i is ancestor of x_m iff $P_{min}(\{x_m, \dots, x_i\}) = x_i$



Proof: a) Use (*). Elements are inserted in order of increasing priorities.

When x_{j} , with $i < j \le m$, is inserted, it traverses the same search path as x_{j} . Hence x_{j} becomes a descendent of x_{j} .

$$k$$
 k < key(x_i)
 x_i goes right
 x_j goes right

$$k \ k > key(x_m)$$

$$x_i \text{ goes left}$$

$$x_j \text{ goes left}$$



Proof: a) (Let *i*<*m*. x_i is ancestor of x_m iff $P_{min}(\{x_i,...,x_m\}) = x_i$) " \Rightarrow " Let $x_j = P_{min}(\{x_i,...,x_m\})$. Show: $x_j = x_j$ Suppose: $x_i \neq x_j$ When x_j is inserted, the tree contains only keys *k* with $k < \text{key}(x_i)$ or $k > \text{key}(x_m)$ All elements of $\{x_i,...,x_m\}\setminus\{x_j\}$ traverse the same search path as x_j : Node with key k < key(x_i): All elements from $\{x_i,...,x_m\}$ turn right. Node with key k > key(x_m): All elements from $\{x_i,...,x_m\}$ turn left.

Hence all elements of $\{x_i, \ldots, x_m\} \setminus \{x_i\}$ become descendents of x_i .

Case 1: $x_i = x_m$ x_i is descendent of x_m Contradiction!

Case 2: $x_i \neq x_m$ x_i and x_m are in different subtrees of x_i Contradiction!

Part b) can be shown analogously.

Let T be a treap with elements $x_1, ..., x_n = x_i$ has *i*-th smallest key

n-th Harmonic number: $H_n = \sum_{k=1}^n 1/k$

Lemma:

- 1. Successful search: The expected number of nodes on the path to x_m is $H_m + H_{n-m+1} 1$.
- 2. Unsuccessful search : Let *m* be the number of keys that are smaller than the search key *k*. The expected number of nodes on the search path is $H_m + H_{n-m}$.

Proof: Part 1

$$X_{m,i} = \begin{cases} 1 & x_i \text{ is ancestor of } x_m \\ 0 & \text{otherwise} \end{cases}$$

 $X_{\rm m}$ = # nodes on the path from the root to x_m (incl. x_m)

$$X_{m} = 1 + \sum_{i < m} X_{m,i} + \sum_{i > m} X_{m,i}$$
$$E[X_{m}] = 1 + E\left[\sum_{i < m} X_{m,i}\right] + E\left[\sum_{i > m} X_{m,i}\right]$$

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i < m :

$$E[X_{m,i}] = \operatorname{Prob}[x_i \text{ is ancestor of } x_m] = 1/(m-i+1)$$

All elements in $\{x_i, ..., x_m\}$ have the same probability of being the one with the smallest priority.

$$Prob[P_{min}(\{x_{i},...,x_{m}\}) = x_{i}] = 1/(m-i+1)$$

$$E[X_{m,i}] = 1/(i-m+1)$$



$$E[X_m] = 1 + \sum_{i < m} \frac{1}{m - i + 1} + \sum_{i > m} \frac{1}{i - m + 1}$$



$$=H_{m}+H_{n-m+1}-1$$

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Part 2

- *m* = 0: Search path is the same as that for x_1 . By Part 1, the expected number of nodes on the search path is $H_1 + H_n 1 = H_n$.
- *m* = *n*: Search path is the same as that for x_n . By Part 1, the expected number of nodes on the search path is $H_n + H_1 1 = H_n$.
- 0 < m < n: x_m is an ancestor of x_{m+1} or vice versa. When searching for k, at every x_i with i < m, the search path turns right x_i with i > m+1, the search path turns left.

Hence the search path for k is the same as that for x_m , x_{m+1} until one of the two keys are hit.

If x_m is hit first, the remaining search path of k is identical to that of x_{m+1} .

If x_{m+1} is hit first, the remaining search path of k is identical to that of x_m .



Hence the length of the search path is upper bounded by that of x_m and x_{m+1} , i.e. max { $H_m + H_{n-m+1} - 1$, $H_{m+1} + H_{n-m} - 1$ } $\leq H_m + H_{n-m}$.

Inserting a new element x

- 1. Choose prio(x).
- 2. Search for the position of *x* in the tree.



- 3. Insert *x* as a leaf.
- 4. Restore the heap property.

while prio(parent(x)) > prio(x) do
 if x is left child then RotateRight(parent(x))
 else RotateLeft(parent(x));

endif endwhile;



Rotations





The rotations maintain the search tree property and restore the heap property.

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Deleting an element x

- 1. Find x in the tree.
- 2. while x is not a leaf do

u := child with smaller priority;

if *u* is left child **then** RotateRight(*x*))

else RotateLeft(*x*);

endif; endwhile;

3. Delete x;









Lemma: The expected running time of insert and delete operations is $O(\log n)$. The expected number of rotations is 2.

Proof: Analysis of insert (delete is the inverse operation) # rotations = depth of x after being inserted as a leaf (1) - depth of x after the rotations (2)

Let $x = x_m$.

- (2) Expected depth is $H_m + H_{n-m+1} 1$.
- (1) Expected depth is $H_{m-1} + H_{n-m} + 1$.

The tree contains *n*-1 elements, *m*-1 of them being smaller.

rotations =
$$H_{m-1} + H_{n-m} + 1 - (H_m + H_{n-m+1} - 1) < 2$$



n = number of elements in treap *T*.

- Minimum(*T*): Return the smallest key. O(log *n*)
- Maximum(*T*): Return the largest key. O(log *n*)
- List(7): Output elements of S in increasing order. O(n)
- Union (T_1, T_2) : Merge T_1 and T_2 . Condition: $\forall x_1 \in T_1$, $x_2 \in T_2$: key $(x_1) < \text{key}(x_2)$
- Split(T, k, T_1, T_2): Split T into T_1 and T_2 . $\forall x_1 \in T_1, x_2 \in T_2$: key(x_1) $\leq k$ and $k < \text{key}(x_2)$



Split(T, k, T_1, T_2): Split T into T_1 and T_2 . $\forall x_1 \in T_1$, $x_2 \in T_2$: key(x_1) $\leq k$ and key(x_2) > k

W.I.o.g. key k is not in T.

Otherwise delete the element with key k and re-insert it into T_1 after the split operation.

- 1. Generate a new element x with key(x) = k and $prio(x) = -\infty$.
- 2. Insert x into T.
- 3. Delete the new root. The left subtree is T_1 , the right subtree is T_2 .



Union (T_1, T_2) : Merge T_1 and T_2 . Condition: $\forall x_1 \in T_1$, $x_2 \in T_2$: key $(x_1) < \text{key}(x_2)$

- 1. Determine key k with $key(x_1) < k < key(x_2)$ for all $x_1 \in T_1$ and $x_2 \in T_2$.
- 2. Generate element x with key(x)=k and $prio(x) = -\infty$.
- 3. Generate treap *T* with root *x*, left subtree T_1 and right subtree T_2 .
- 4. Delete *x* from *T*.





Lemma: The expected running time of the operations Union and Split is O(log *n*).



Priorities from [0,1)

Priorities are used only when two elements are compared to find out which of them has the higher priority.

In case of equality, extend both priorities by bits chosen uniformly at random until two corresponding bits differ.

 $p_1 = 0.010111001$ $p_2 = 0.010111001$ $p_1 = 0.010111001011$ $p_2 = 0.010111001010$