

# 11 – Dynamic Programming (1) Introduction Weighted Interval Scheduling





- General approach, differences to a recursive solution
- Basic example: Computation of the Fibonacci numbers
- Weighted interval scheduling



**Recursive approach:** Solve a problem by solving several smaller analogous subproblems of the same type. Then combine these solutions to generate a solution to the original problem.

Drawback: Repeated computation of solutions

**Dynamic-programming method:** Once a subproblem has been solved, store its solution in a table so that it can be retrieved later by simple table lookup.

# **Example: Fibonacci numbers**

$$f(0) = 0$$
  

$$f(1) = 1$$
  

$$f(n) = f(n-1) + f(n-2), \text{ for } n \ge 2$$

Remark:

$$f(n) = \left[\frac{1}{\sqrt{5}} \left(\frac{1+\sqrt{5}}{2}\right)^n\right]$$

### Straightforward implementation:

```
procedure fib (n : integer) : integer

if (n = 0) or (n = 1)

then return n;

else return fib(n - 1) + fib(n - 2);
```

# Fibonacci numbers



Recursion tree: fib(5)fib(3) fib(4)fib(3) fib(2) fib(1) fib(2)fib(1)fib(0) fib(2)fib(1) fib(1)fib(0)fib(1) fib(0)

**Repeated computation!** 

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## Approach:

- 1. Recursively define problem P.
- 2. Determine a set *T* consisting of all subproblems that have to be solved during the computation of a solution to *P*.
- 3. Find an order  $T_0$ , ...,  $T_k$  of the subproblems in T such that during the computation of a solution to  $T_i$  only subproblems  $T_j$  with j < i arise.
- 4. Solve  $T_0, ..., T_k$  in this order and store the solutions.

- 1. Recursive definition of the Fibonacci numbers, based on the standard equation.
- 2.  $T = \{f(0), \dots, f(n)\}$
- 3.  $T_i = f(i), \quad i = 0,...,n$
- 4. Computation of *fib*(*i*), for  $i \ge 2$ , only requires the results of the last two subproblems *fib*(*i* 1) and *fib*(*i* 2).

Computation by dynamic programming, version 1:

procedure fib(n : integer) : integer

- 1 F[0] := 0; F[1] := 1;
- 2 **for** *k* := 2 **to** *n* **do**
- 3 F[k] := F[k-1] + F[k-2];
- 4 **return** *F*[*n*];



Computation by dynamic programming, version 2:

procedure fib (n : integer) : integer

- 1 *F*(*secondlast*) := 0; *F*(*last*) :=1;
- 2 **for** *k* := 2 **to** *n* **do**
- 3 F(current) := F(last) + F(secondlast);
- 4 F(secondlast) := F(last);
- 5 F(last) := F(current);
- 6 if  $n \le 1$  then return *n* else return *F*(*current*);

Linear running time, constant space requirement!



Compute each number exactly once, store it in an array *F*[0...*n*]: **procedure** *fib* (*n* : *integer*) : *integer* 

- 1 F[0] := 0; F[1] := 1;
- 2 **for** *i* :=2 **to** *n* **do**
- $3 \qquad F[i] := \infty;$
- 4 **return** *lookupfib(n*);

The procedure *lookupfib* is defined as follows:

### procedure lookupfib(k : integer) : integer

- 1 if  $F[k] < \infty$
- 2 then return F[k];
- 3 **else** F[k] := lookupfib(k-1) + lookupfib(k-2);
- 4 **return** *F*[*k*];

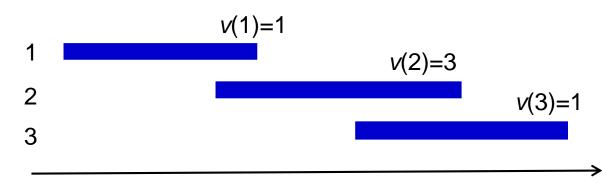


**Problem:** Set  $S = \{1, ..., n\}$  of *n* requests for a resource. Request *i*: [s(i), f(i)) s(i) = start time f(i) = finish time v(i) = value/weight

Two requests are compatible if they do not overlap.

**Goal:** Select  $S \subseteq \{1,...,n\}$  of mutually compatible requests so as to maximize  $\sum_{i \in S} v(i)$ .

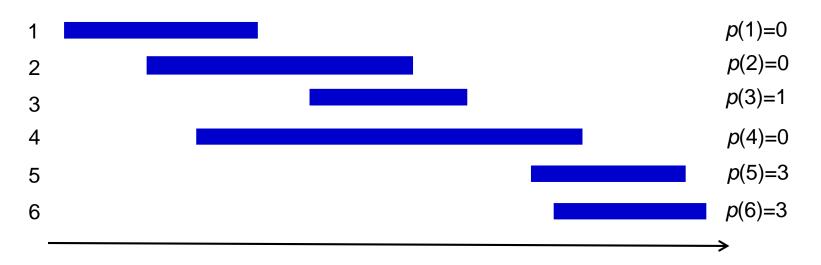
Greedy\* (Earliest Deadline First) is not optimal.





In the following, requests are numbered such that  $f(1) \leq f(2) \leq f(3) \leq \dots \leq f(n)$ .

For j = 1,...,n p(j) = largest i < j such that requests i and j do not overlap p(j) = 0 if no request i < j is disjoint from j



Dynamic programming approach

O = optimal subset of requests

- $n \notin O$ : O is an optimal subset of  $\{1, \dots, n-1\}$
- $n \in O$ : remaining requests in O are an optimal subset of  $\{1, ..., p(n)\}$

For j = 1,...,n  $O_j = \text{optimal subset}$  of requests from  $\{1,...,j\}$ OPT(j) = value of an optimal solution OPT(0) := 0

- $j \notin O_j$ :  $O_j$  is an optimal subset of  $\{1, \dots, j-1\}$
- $j \in O_j$ : remaining requests in  $O_j$  are an optimal subset of  $\{1, \dots, p(j)\}$

# Dynamic programming approach

For *j* = 1,...,*n* 

 $O_j$  = optimal subset of requests from {1,...,j}

**OPT(***j***) = value** of an optimal solution **OPT(**0**)** := 0

- $j \notin O_j$ :  $O_j$  is an optimal subset of  $\{1, \dots, j-1\}$
- $j \in O_j$ : remaining requests in  $O_j$  are an optimal subset of  $\{1, \dots, p(j)\}$

 $OPT(j) = \max\{ v(j) + OPT(p(j)), OPT(j-1) \}$ 

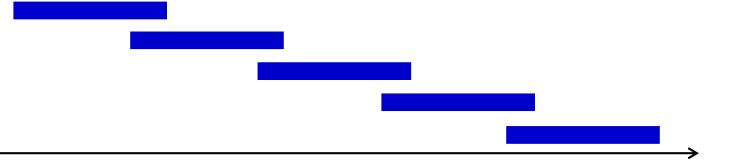
Request *j* belongs to an optimal solution for  $\{1, ..., j\}$  if and only if  $v(j) + OPT(p(j)) \ge OPT(j-1)$ .



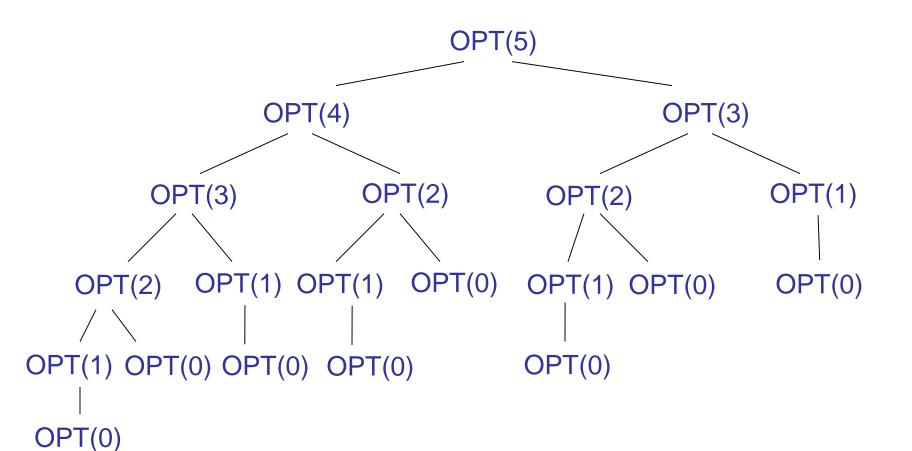
Assume that values p(j), for j=1,...,n, have been computed.

procedure ComputeOpt(j : integer)

- 1 **if** j = 0
- 2 then return 0;
- 3 **else return** max{v(j) + ComputeOPT(p(j)), ComputeOPT(j-1)};



## Instance taking exponential time





Array M[0..*n*] contains the values of the optimal solutions.

procedure ComputeOpt(n : integer)

- 1 M[0] := 0;
- 2 **for** *j* := 1 **to** *n* **do**
- 3  $M[j] := \max\{v(j) + M[p(j)], M[j-1]\};$
- 4 endfor;

Running time: O(*n*)



- 1 **if** *j* = 0 **then**
- 2 return 0;
- 3 else if M[j] is not empty then
- 4 return M[*j*];
- 5 **else**
- 6  $M[j] := \max\{v(j) + ComputeOPT(p(j)), ComputeOpt(j-1)\};$
- 7 return M[*j*];
- 8 endif;
- **Proposition:** The running time of ComputeOpt(*n*) is O(*n*) if the requests are sorted in order of non-decreasing finish times and the values p(j),  $1 \le j \le n$ , are computed.
- **Proof:** The running time is a constant times the number of recursive calls to ComputeOpt. Two calls are issued whenever a new array entry is filled. Hence there are a total of at most 2*n* calls.

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procedure FindSolution(j : integer)

- 1 **if** *j* = 0 **then**
- 2 Output nothing;
- 3 else if  $v(j) + M[p(j)] \ge M[j-1]$  then
- 4 Output *j* together with the result of FindSolution(p(j));
- 5 **else**
- 6 Output the result of FindSolution(*j*-1);
- 7 endif;

FindSolution calls itself only on strictly smaller values. Therefore FindSolution(n) issues less than n recursive calls and the running time is O(n).