There are many practically important optimization problems that are NP-hard.

#### What can we do?

- Heuristics.
- Exploit special structure of instances occurring in practise.
- Consider algorithms that do not compute the optimal solution but provide solutions that are close to optimum.

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# Why approximation algorithms?

- We need algorithms for hard problems.
- lt gives a rigorous mathematical base for studying heuristics.
- It provides a metric to compare the difficulty of various optimization problems.
- Proving theorems may give a deeper theoretical understanding which in turn leads to new algorithmic approaches.

# Why not?

Sometimes the results are very pessimistic due to the fact that an algorithm has to provide a close-to-optimum solution on every instance.

#### **Definition 57**

An  $\alpha$ -approximation for an optimization problem is a polynomial-time algorithm that for all instances of the problem produces a solution whose value is within a factor of  $\alpha$  of the value of an optimal solution.

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#### **Definition 58**

An optimization problem P = (1, sol, m, goal) is in **NPO** if

- $x \in I$  can be decided in polynomial time
- ▶  $y \in sol(I)$  can be verified in polynomial time
- lacktriangleright m can be computed in polynomial time
- ▶  $goal \in \{min, max\}$

In other words: the decision problem is there a solution y with m(x,y) at most/at least z is in NP.

- ► *x* is problem instance
- $\triangleright$   $\gamma$  is candidate solution
- $ightharpoonup m^*(x)$  cost/profit of an optimal solution

#### **Definition 59 (Performance Ratio)**

$$R(x,y) := \max \left\{ \frac{m(x,y)}{m^*(x)}, \frac{m^*(x)}{m(x,y)} \right\}$$

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## **Definition 61 (PTAS)**

input  $x \in \mathcal{I}$  and  $\epsilon > 0$  and produces a solution  $\gamma$  for x with

$$R(x, y) \le 1 + \epsilon$$

The running time is polynomial in |x|.

approximation with arbitrary good factor... fast?

# **Definition 60** ( $\gamma$ -approximation)

An algorithm A is an  $\gamma$ -approximation algorithm iff

$$\forall x \in \mathcal{I} : R(x, A(x)) \leq r$$
,

and A runs in polynomial time.

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A PTAS for a problem P from NPO is an algorithm that takes as

$$R(x, y) \leq 1 + \epsilon$$
.

# Problems that have a PTAS

**Scheduling**. Given m jobs with known processing times; schedule the jobs on n machines such that the MAKESPAN is minimized.

#### **Definition 62 (FPTAS)**

An FPTAS for a problem P from NPO is an algorithm that takes as input  $x \in \mathcal{I}$  and  $\epsilon > 0$  and produces a solution y for x with

$$R(x, y) \leq 1 + \epsilon$$
.

The running time is polynomial in |x| and  $1/\epsilon$ .

approximation with arbitrary good factor... fast!



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# **Definition 63 (APX - approximable)**

A problem P from NPO is in APX if there exist a constant  $r \ge 1$  and an r-approximation algorithm for P.

constant factor approximation...

#### Problems that have an FPTAS

**KNAPSACK**. Given a set of items with profits and weights choose a subset of total weight at most W s.t. the profit is maximized.

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#### Problems that are in APX

**MAXCUT.** Given a graph G = (V, E); partition V into two disjoint pieces A and B s.t. the number of edges between both pieces is maximized.

**MAX-3SAT**. Given a 3CNF-formula. Find an assignment to the variables that satisfies the maximum number of clauses.

## Problems with polylogarithmic approximation guarantees

- Set Cover
- Minimum Multicut
- Sparsest Cut
- ► Minimum Bisection

There is an r-approximation with  $r \leq \mathcal{O}(\log^{c}(|x|))$  for some constant c.

Note that only for some of the above problem a matching lower bound is known.

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# There are weird problems!

Asymmetric k-Center admits an  $\mathcal{O}(\log^* n)$ -approximation.

There is no  $o(\log^* n)$ -approximation to Asymmetric k-Center unless  $NP \subseteq DTIME(n^{\log \log \log n})$ .

# There are really difficult problems!

#### **Theorem 64**

For any constant  $\epsilon > 0$  there does not exist an  $\Omega(n^{1-\epsilon})$ -approximation algorithm for the maximum clique problem on a given graph G with n nodes unless P = NP.

Note that an n-approximation is trivial.

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Class APX not important in practise.

Instead of saying problem P is in APX one says problem P admits a 4-approximation.

One only says that a problem is APX-hard.

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