Knapsack:

Given a set of items $\{1,\ldots,n\}$, where the i-th item has weight $w_i \in \mathbb{N}$ and profit $p_i \in \mathbb{N}$, and given a threshold W. Find a subset $I \subseteq \{1,\ldots,n\}$ of items of total weight at most W such that the profit is maximized (we can assume each $w_i \leq W$).

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```
Algorithm 1 Knapsack
1: A(1) \leftarrow [(0,0), (p_1, w_1)]
2: for j \leftarrow 2 to n do
3: A(j) \leftarrow A(j-1)
4: for each (p, w) \in A(j-1) do
             if w + w_i \leq W then
                    add (p + p_i, w + w_i) to A(j)
              remove dominated pairs from A(j)
8: return \max_{(p,w)\in A(n)} p
```

The running time is $\mathcal{O}(n \cdot \min\{W, P\})$, where $P = \sum_i p_i$ is the total profit of all items. This is only pseudo-polynomial.

Definition 74

An algorithm is said to have pseudo-polynomial running time if the running time is polynomial when the numerical part of the input is encoded in unary.

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$$\ge (1 - \epsilon) \text{OPT}.$$

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Together with the obervation that if each $p_i \ge \frac{1}{3}C_{\max}^*$ then LPT is optimal this gave a 4/3-approximation.

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1. Find the optimum Makespan for the long jobs by brute force.

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Idea:

- 1. Find the optimum Makespan for the long jobs by brute force.
- 2. Then use the list scheduling algorithm for the short jobs, always assigning the next job to the least loaded machine.

We still have a cost of

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If ℓ is a short job its length is at most

$$p_\ell \leq \sum_j p_j/(mk)$$

which is at most C_{max}^*/k .

Hence we get a schedule of length at most

$$\left(1+\frac{1}{k}\right)C_{\max}^*$$

There are at most km long jobs. Hence, the number of possibilities of scheduling these jobs on m machines is at most m^{km} , which is constant if m is constant. Hence, it is easy to implement the algorithm in polynomial time.

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The above algorithm gives a polynomial time approximatior scheme (PTAS) for the problem of scheduling n jobs on m identical machines if m is constant.

We choose $k = \lceil \frac{1}{\epsilon} \rceil$.



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- ▶ We round all long jobs down to multiples of T/k^2 .
- For these rounded sizes we first find an optimal schedule.
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After the first phase the rounded sizes of the long jobs assigned to a machine add up to at most T.

There can be at most k (long) jobs assigned to a machine as otw. their rounded sizes would add up to more than T (note that the rounded size of a long job is at least T/k).

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Assigning the current (short) job to such a machine gives that the new load is at most

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Hence, any large job has rounded size of $\frac{i}{k^2}T$ for $i \in \{k, ..., k^2\}$. Therefore the number of different inputs is at most n^{k^2} (described by a vector of length k^2 where, the i-th entry describes the number of jobs of size $\frac{i}{k^2}T$). This is polynomial.

The schedule/configuration of a particular machine x can be described by a vector of length k^2 where the i-th entry describes the number of jobs of rounded size $\frac{i}{k^2}T$ assigned to x. There are only $(k+1)^{k^2}$ different vectors.

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If $OPT(n_1, \ldots, n_{k^2}) \leq m$ we can schedule the input.

We have

 $OPT(n_1,\ldots,n_{k^2})$

$$= \begin{cases} 0 & (n_1, \dots, n_{k^2}) = 0 \\ 1 + \min_{(s_1, \dots, s_{k^2}) \in C} \text{OPT}(n_1 - s_1, \dots, n_{k^2} - s_{k^2}) & (n_1, \dots, n_{k^2}) \geq 0 \\ \infty & \text{otw.} \end{cases}$$

where C is the set of all configurations

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- Suppose we have an instance with polynomially bounded processing times $p_i \le q(n)$
- We set $k := \lceil 2nq(n) \rceil \ge 2 \text{ OPT}$
- ▶ Then

$$\mathsf{ALG} \leq \left(1 + \frac{1}{k}\right)\mathsf{OPT} \leq \mathsf{OPT} + \frac{1}{2}$$

- But this means that the algorithm computes the optimal solution as the optimum is integral.
- This means we can solve problem instances if processing times are polynomially bounded
- Running time is $\mathcal{O}(\text{poly}(n, k)) = \mathcal{O}(\text{poly}(n))$
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More General

Let $OPT(n_1, ..., n_A)$ be the number of machines that are required to schedule input vector $(n_1, ..., n_A)$ with Makespan at most T (A: number of different sizes).

If $OPT(n_1,...,n_A) \leq m$ we can schedule the input

$$OPT(n_1, ..., n_A) = \begin{cases}
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where C is the set of all configurations

 $|C| \le (B+1)^A$, where B is the number of jobs that possibly can fit on the same machine.

The running time is then $O((B+1)^A n^A)$ because the dynamic programming table has just n^A entries.

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Given n items with sizes s_1, \ldots, s_n where

$$1 > s_1 \ge \cdots \ge s_n > 0$$
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Pack items into a minimum number of bins where each bin can hold items of total size at most 1.

Theorem 77

There is no ρ -approximation for Bin Packing with $\rho < 3/2$ unless P = NP.

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Proof

$$\sum_{i \in S} b_i = \sum_{i \in T} b_i \quad ?$$

- We can solve this problem by setting $s_i := 2b_i/B$ and asking whether we can pack the resulting items into 2 bins or not.
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An asymptotic polynomial-time approximation scheme (APTAS) is a family of algorithms $\{A_\epsilon\}$ along with a constant c such that A_ϵ returns a solution of value at most $(1+\epsilon)\mathrm{OPT}+c$ for minimization problems.

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Again we can differentiate between small and large items.

Lemma 79

Any packing of items into ℓ bins can be extended with items of size at most γ s.t. we use only $\max\{\ell,\frac{1}{1-\gamma}\mathrm{SIZE}(I)+1\}$ bins, where $\mathrm{SIZE}(I)=\sum_i s_i$ is the sum of all item sizes.

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- ► Hence, $r(1 y) \le SIZE(I)$ where r is the number of nearly-full bins.



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- ► Hence, $r(1 \gamma) \le \text{SIZE}(I)$ where r is the number of nearly-full bins.
- This gives the lemma.



Choose $y = \epsilon/2$. Then we either use ℓ bins or at most

$$\frac{1}{1 - \epsilon/2} \cdot \text{OPT} + 1 \le (1 + \epsilon) \cdot \text{OPT} + 1$$

bins.

It remains to find an algorithm for the large items.

Linear Grouping:

Generate an instance I' (for large items) as follows.

- Order large items according to size.
- Let the first *k* items belong to group 1; the following *k* items belong to group 2; etc.
- Delete items in the first group;
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9. Jul. 2022

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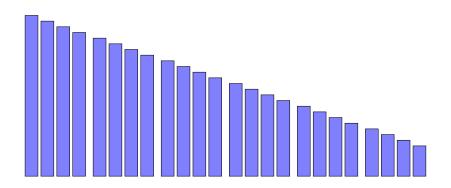
Generate an instance I' (for large items) as follows.

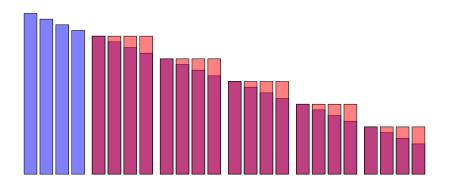
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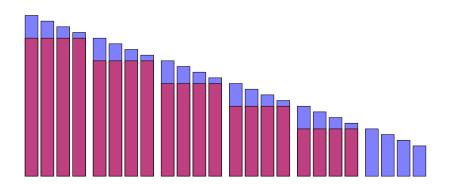
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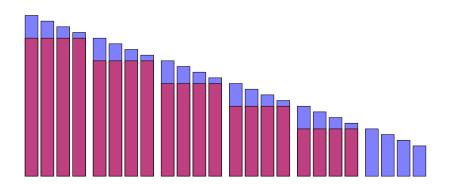
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$$\mathsf{OPT}(I') \leq \mathsf{OPT}(I) \leq \mathsf{OPT}(I') + k$$

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We set $k = \lfloor \epsilon \text{SIZE}(I) \rfloor$.

Then $n/k \le n/\lfloor \epsilon^2 n/2 \rfloor \le 4/\epsilon^2$ (note that $\lfloor \alpha \rfloor \ge \alpha/2$ for $\alpha \ge 1$).

Hence, after grouping we have a constant number of piece sizes $(4/\epsilon^2)$ and at most a constant number $(2/\epsilon)$ can fit into any bin.

We can find an optimal packing for such instances by the previous Dynamic Programming approach.

cost (for large items) at most

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Can we do better?

In the following we show how to obtain a solution where the number of bins is only

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Configuration LP

Change of Notation:

- Group pieces of identical size.
- Let s_1 denote the largest size, and let b_1 denote the number of pieces of size s_1 .
- \triangleright s_2 is second largest size and b_2 number of pieces of size s_2 ;
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A possible packing of a bin can be described by an m-tuple (t_1, \ldots, t_m) , where t_i describes the number of pieces of size s_i . Clearly.

$$\sum_i t_i \cdot s_i \leq 1 \ .$$

We call a vector that fulfills the above constraint a configuration.

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Let N be the number of configurations (exponential)

Let $T_1, ..., T_N$ be the sequence of all possible configurations (a configuration T_j has T_{ji} pieces of size s_i).

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How to solve this LP?

later...

We can assume that each item has size at least $1/\mathrm{SIZE}(I)$.

- Sort items according to size (monotonically decreasing).
- Process items in this order; close the current group if size of items in the group is at least 2 (or larger). Then open new group.
- ▶ I.e., G_1 is the smallest cardinality set of largest items s.t. total size sums up to at least 2. Similarly, for G_2, \ldots, G_{r-1} .
- ▶ Only the size of items in the last group G_r may sum up to less than 2.

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- Round all items in a group to the size of the largest group member.
- ▶ Delete all items from group G_1 and G_r .
- For groups G_2, \ldots, G_{r-1} delete $n_i n_{i-1}$ items.
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$$3\frac{n_i - n_{i-1}}{n_i} \le \sum_{j=n_{i-1}+1}^{n_i} \frac{3}{j}$$

since the average piece size is only $3/n_i$.

Summing over all i that have $n_i > n_{i-1}$ gives a bound of at most

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Algorithm 1 BinPack

- 1: **if** SIZE(I) < 10 **then**
- 2: pack remaining items greedily
- 3: Apply harmonic grouping to create instance I'; pack discarded items in at most $\mathcal{O}(\log(\text{SIZE}(I)))$ bins.
- 4: Let x be optimal solution to configuration LP
- 5: Pack $\lfloor x_j \rfloor$ bins in configuration T_j for all j; call the packed instance I_1 .
- 6: Let I_2 be remaining pieces from I'
- 7: Pack I_2 via BinPack (I_2)

$$\mathsf{OPT}_{\mathsf{LP}}(I_1) + \mathsf{OPT}_{\mathsf{LP}}(I_2) \leq \mathsf{OPT}_{\mathsf{LP}}(I') \leq \mathsf{OPT}_{\mathsf{LP}}(I)$$

Proof:

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Each level of the recursion partitions pieces into three types

- 1. Pieces discarded at this level.
- **2.** Pieces scheduled because they are in I_1 .
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Pieces of type 2 summed over all recursion levels are packed into at most $\mathrm{OPT}_{\mathrm{LP}}$ many bins.

Pieces of type 1 are packed into at most

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How to solve the LP?

Let $T_1, ..., T_N$ be the sequence of all possible configurations (a configuration T_j has T_{ji} pieces of size s_i).

In total we have b_i pieces of size s_i .

Primal

$$\begin{array}{lll} \min & \sum_{j=1}^N x_j \\ \text{s.t.} & \forall i \in \{1 \dots m\} & \sum_{j=1}^N T_{ji} x_j & \geq & b_i \\ & \forall j \in \{1, \dots, N\} & x_j & \geq & 0 \end{array}$$

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