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Proof.

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Proof.

- We can find the shortest augmenting paths in time $\mathcal{O}(m)$ via BFS.
- O(m) augmentations for paths of exactly k < n edges.



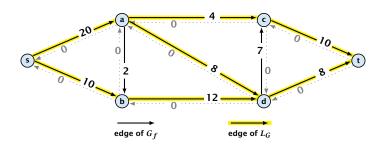
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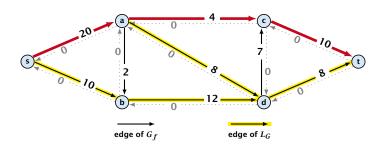
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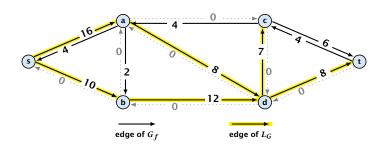
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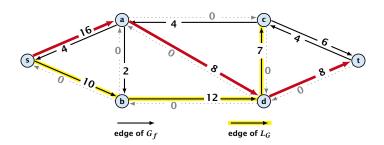
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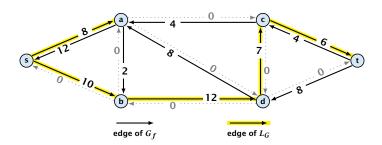
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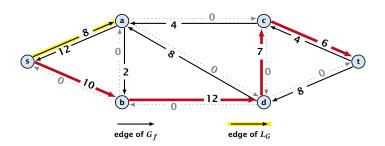
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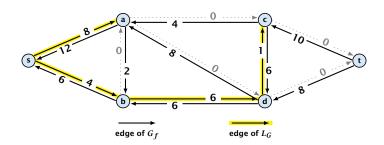
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In the following we assume that the residual graph \mathcal{G}_f does not contain zero capacity edges.

This means, we construct it in the usual sense and then delete edges of zero capacity.

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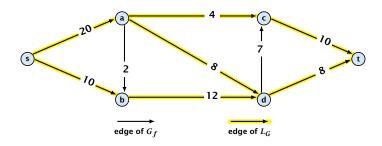
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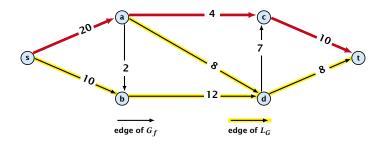


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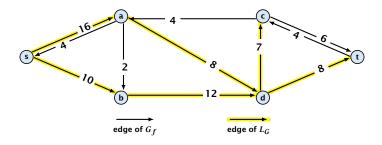


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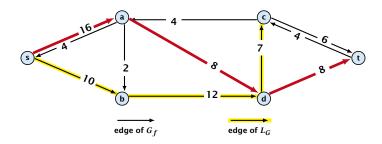


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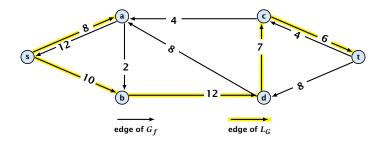


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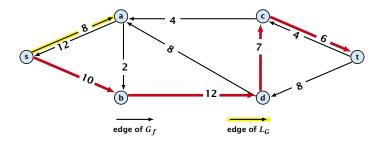


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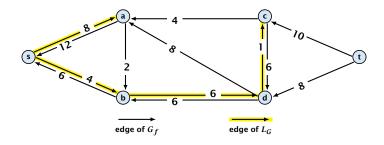


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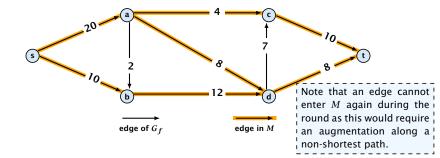
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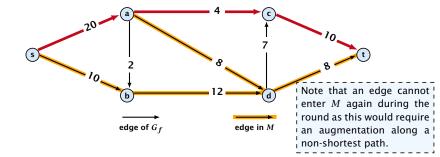
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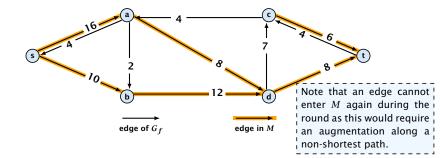
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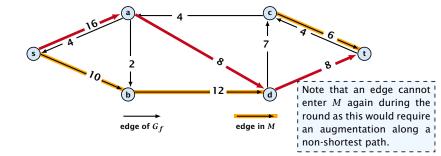
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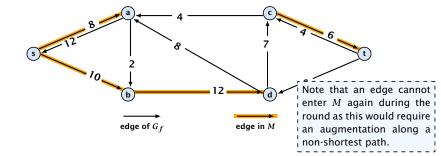
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Theorem 45

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Theorem 46 (without proof)

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Note:

There always exists a set of m augmentations that gives a maximum flow (why?).

When sticking to shortest augmenting paths we cannot improve (asymptotically) on the number of augmentations.

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However, we can improve the running time to $\mathcal{O}(mn^2)$ by improving the running time for finding an augmenting path (currently we assume $\mathcal{O}(m)$ per augmentation for this).

We maintain a subset M of the edges of G_f with the guarantee that a shortest s-t path using only edges from M is a shortest augmenting path.

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Note that ${\cal M}$ is not the set of edges of the level graph but a subset of level-graph edges.

M is initialized as the level graph L_G .

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Either you find t after at most n steps, or you end at a node v that does not have any outgoing edges.

You can delete incoming edges of v from M.

Let a phase of the algorithm be defined by the time between two augmentations during which the distance between \emph{s} and \emph{t} strictly increases.

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The total cost for performing an augmentation during a phase is only $\mathcal{O}(n)$. For every edge in the augmenting path one has to update the residual graph G_f and has to check whether the edge is still in M for the next search.

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There are at most n phases. Hence, total cost is $O(mn^2)$.